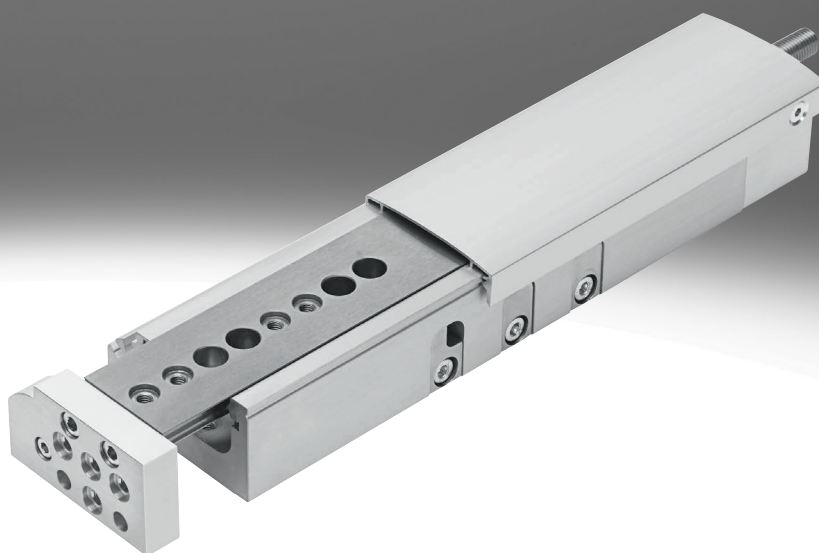


Mini slides DGSL

FESTO

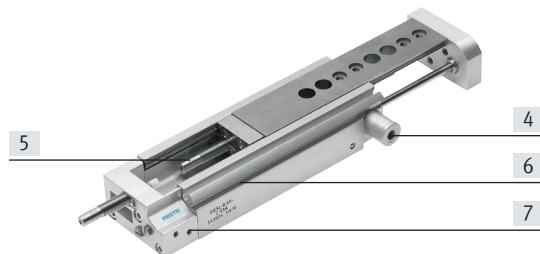
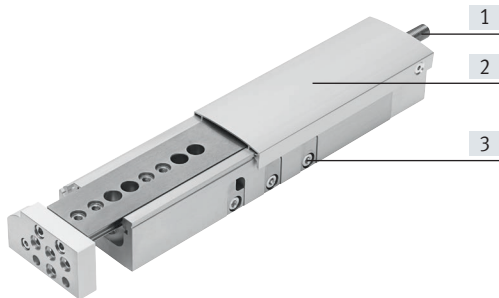


Key features

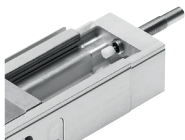
General

- Double-acting drives
- Wide range of mounting options
- System product for handling and assembly technology
- Very flexible thanks to versatile assembly and mounting options on:
 - Drive body, slide, yoke plate

The technology in detail



[1] Cushioning



- Choice of five cushioning types:
 - Elastic cushioning without metal end position (P)
 - Elastic cushioning without metal end position, short design (E)
 - Elastic cushioning with metal end position (P1)
 - Shock absorber (Y3)
 - Shock absorber with reducing sleeve (Y11)
- Alternatives:
 - Without cushioning (N)

[2] Cover

→ Page 47



- The cover stops foreign parts or dirt getting into the guide
- The cover comes in different lengths and can be shortened as required by the customer

[3] Rough stroke adjustment

→ Page 10



- The end stop for the advanced end position can be adjusted mechanically, for example to shorten the stroke

[4] Clamping unit

→ Page 40



- Mechanical clamping for fixing the slide in any position; frictional locking (C)

[4] End-position locking

→ Page 40



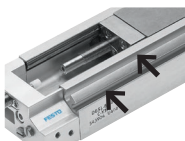
- Mechanical locking when the end position is reached, for fixing the slide in the unpressurised, retracted state; positive locking (E3)

[5] Innovative guide unit



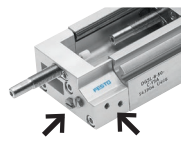
- Wide roller track, providing extremely high rigidity
- High load capacity
- High precision
- Housing and steel slide form a guide, there are no accumulative tolerances

[6] Position sensing



- Proximity switches can be integrated, so there are no projecting parts
- Two slots for mounting
- Clearly visible from the side and from above

[7] Supply ports



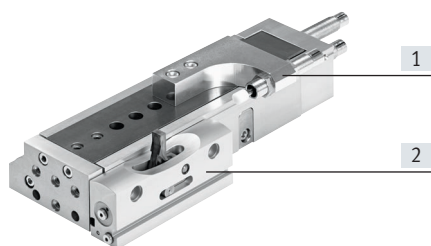
- Choice of two sides:
 - On the front
 - On the side

System example

The technology in detail

Intermediate-position module

→ Page 48

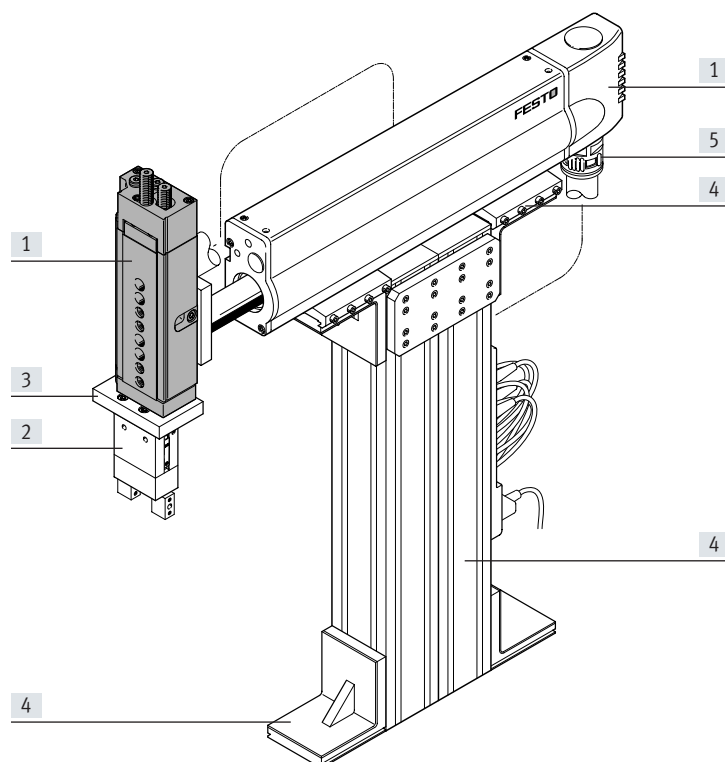


The intermediate-position module enables an additional adjustable position within the stroke range.

- [1] Shock absorber retainer
- [2] Intermediate-position module

- The symmetrical design means that the intermediate position can be approached when advancing or retracting, depending on the assembly
- Can be travelled through from the end position
- Possible to continue on directly from the intermediate position
- Easy to assemble
- Sensing of the stop lever position is possible

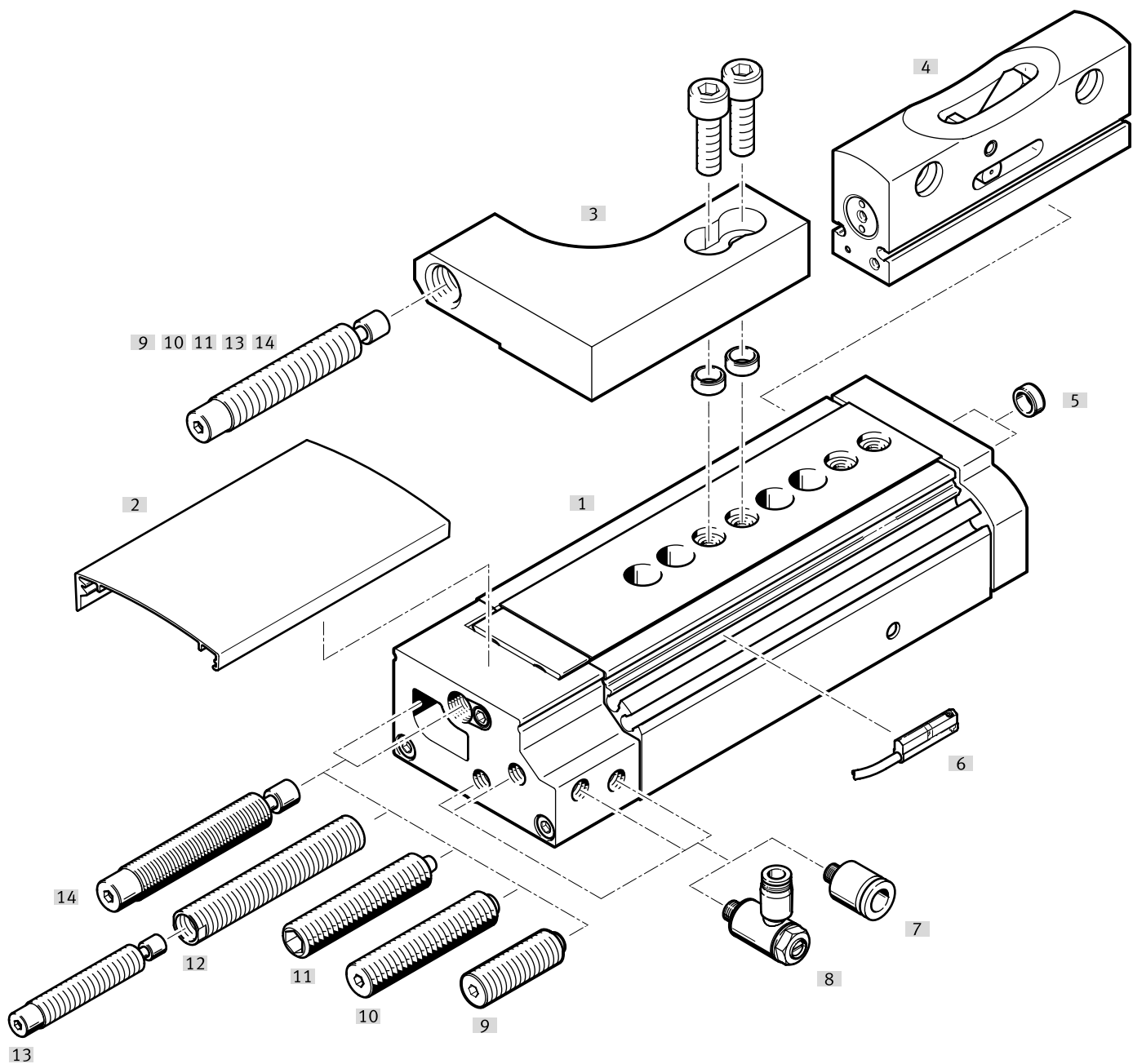
System product for handling and assembly technology



System components and accessories

	Description	→ Page/Internet
[1] Drives	Wide range of combinations possible within handling and assembly systems	drive
[2] Gripper	Wide range of variations possible within handling and assembly technology	gripper
[3] Adapter	For drive/drive connections	adapter kit
	For drive/gripper connections	
[4] Basic components	Profiles and profile connections as well as profile/drive connections	basic component
[5] Installation components	For a clear, safe installation of electrical cables and tubes	installation component
– Axes	Wide range of combinations possible within handling and assembly systems	axis
– Motors	Servo and stepper motors, with or without gear unit	motor

Peripherals overview



 **Note**
Operation without cushioning components is not permitted.

Peripherals overview

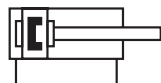
Accessories		Description	→ Page/Internet
[1]	Mini slide DGSL	Double-acting	
[2]	Covering DADS	- For protection, to stop foreign parts or dirt getting into the guide - The cover can be shortened as required by the customer	47
[3]	Shock absorber retainer DADP	- Attachment for the shock absorber - For positioning and cushioning the intermediate position	50
[4]	Intermediate-position module DADM	With stop lever for the intermediate position	48
[5]	Centring sleeve ZBH	For centring loads and attachments (centring sleeves are included in the scope of delivery of the mini slide)	52
[6]	Proximity switch SME/SMT-10	For position sensing Can be integrated in the sensor slot, so it does not protrude	52
[7]	Push-in fitting QSM	For connecting tubing with standard O.D.	52
[8]	One-way flow control valve GRLA	For regulating speed	52
[9]	Cushioning E	Elastic stop for medium loads at medium speed	51
[10]	Cushioning P	Elastic stop for medium loads at medium speed	51
[11]	Cushioning with stop P1	Precision metal stop for small loads at low speed	51
[12]	Reducing sleeve DAYH	For installing a smaller shock absorber. For applications in which the cushioning energy is between cushioning Y3 and P1	51
[13]	Shock absorber DYSW	→ Page (shock absorber selection)	51
[14]	Cushioning with shock absorber Y3	For large loads and high speed. Ensures precise, metal-to-metal contact after the cushioning	51
–	Distance sensor SOIA	For monitoring the condition of the damping elements	51

Type codes

001	Series	
DGSL	Mini slide, double-acting	
002	Size	
4	4	
6	6	
8	8	
10	10	
12	12	
16	16	
20	20	
25	25	
003	Stroke	
...	10 ... 200	
004	Clamping unit	
	None	
C	Attached	
005	End-position locking	
	None	
E3	With retracted piston rod	
006	Cushioning	
N	No cushioning	
P	Elastic cushioning rings/plates on both sides	
P1	Elastomer cushioning, adjustable on both sides, with fixed stop	
Y3	Shock absorber, self-adjusting, progressive, at both ends	
E	Elastomer cushioning, short, on both sides	
Y11	Shock absorber, self-adjustable, progressive at both ends, with reducing sleeve	
007	Position sensing	
A	For proximity sensor	

Datasheet

Function



-  Size
4 ... 25
-  Stroke length
10 ... 200 mm

Sets of wearing parts

→ Page 45



General technical data

Size		4	6	8	10	12	16	20	25
Pneumatic connection		M3			M5			G1/8	
Design		Scotch yoke system							
Guide		Ball bearing cage guide							
Type of mounting		With through-hole							
		With female thread							
Cushioning	P	Elastic cushioning without metal end position, at both ends							
	E	Elastic cushioning without metal end position, at both ends, short design							
	P1	Elastic cushioning with metal end position, at both ends, adjustable							
	Y3	–			Progressive shock absorber, at both ends				
	Y11	–			Progressive shock absorber with reducing sleeve, at both ends				
	N	No cushioning							
Position sensing		Via proximity switch							
Mounting position		Any							
Max. advancing speed	[m/s]	0.5			0.8				
Max. retracting speed	[m/s]	0.5			0.8				
Repetition accuracy	P1/Y3	[mm]	±0.01						
	P	[mm]	0.3						

Operating and environmental conditions

Size	4	6	8	10	12	16	20	25
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]							
Note on the operating/pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)							
Min. operating pressure								
	[MPa]	0.25	0.15	0.1				
	[bar]	2.5	1.5	1				
Max. operating pressure1)								
	[MPa]	0.8						
	[bar]	8						
Ambient temperature2)	[°C]	0 ... +60						

1) Note max. operating pressure in combination with the intermediate-position module DADM-EP → Internet: dadma

2) Note operating range of proximity switches

Piston diameter, forces and impact energy

Size	4	6	8	10	12	16	20	25
Piston Ø	[mm]	6	8	10	12	16	25	32
Theoretical force at 0.6 MPa (6 bar), advancing	[N]	17	30	47	68	121	295	483
Theoretical force at 0.6 MPa (6 bar), retracting	[N]	13	23	40	51	104	247	415
Impact energy in the end positions	P, E	[Nm]	0.015	0.05	0.08	0.12	0.25	0.45
	P1	[Nm]	0.005	0.02	0.03	0.04	0.06	0.12
	Y3	[Nm]	–	–	0.8	1.3	2.5	4
	1)	[Nm]	–	–	–	0.8	1.3	2.5

1) With reducing sleeve and next smaller shock absorber.

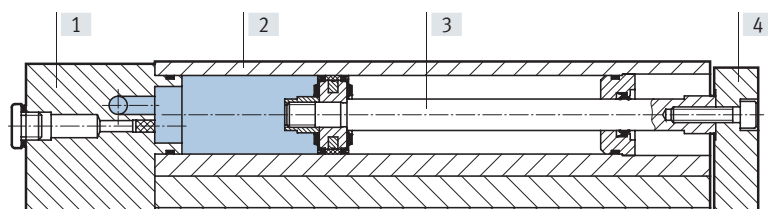
Datasheet

Weight [g] Size	Stroke	4	6	8	10	12	16	20	25
Product weight without cushioning component									
	10	82	158	235	396	604	896	1535	2520
	20	93	179	263	434	660	954	1649	2670
	30	104	197	289	470	711	1008	1746	2824
	40	–	215	313	507	762	1072	1857	2983
	50	–	232	370	548	813	1143	1991	3137
	80	–	–	454	727	1112	1 365	2295	4019
	100	–	–	–	813	1229	1712	2921	4519
	150	–	–	–	–	1499	2034	3620	5344
	200	–	–	–	–	–	–	4248	6139
Moving mass without cushioning component									
	10	31	68	101	163	256	403	660	998
	20	34	76	111	180	279	432	710	1052
	30	38	83	121	194	299	459	750	1115
	40	–	90	130	208	320	486	801	1181
	50	–	99	152	226	340	519	858	1244
	80	–	–	185	299	456	618	998	1567
	100	–	–	–	334	507	776	1254	1761
	150	–	–	–	–	614	910	1566	2102
	200	–	–	–	–	–	–	1807	2432
Cushioning component									
	P	2	3.6	6	14	23	45.6	82.4	106
	E	1	2	3	9	12	15	31	40
	P1	1.6	3	5	12	19.7	39.6	77.3	104
	Y3	–	–	6	11	21	42	67	91
	1)	–	–	–	18	33	52	91	131

1) With reducing sleeve and next smaller shock absorber.

Materials

Sectional view



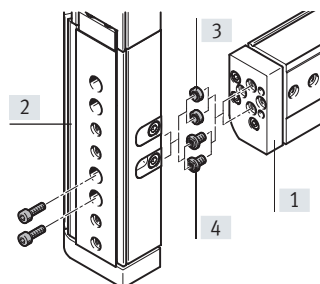
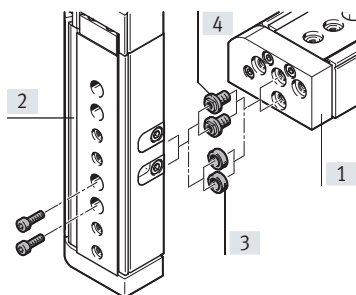
Mini slide

[1]	Cover	Anodised aluminium
[2]	Housing	Anodised aluminium
[3]	Piston rod	High-alloy steel
[4]	Yoke plate	Anodised aluminium
–	Guide	Tempered steel
	Seals	Thermoplastic rubber, hydrogenated nitrile rubber, nitrile rubber
	Cleanroom class	Class 7 to ISO 14644-1
	LABS (PWIS) conformity	VDMA24364-B1/B2-L

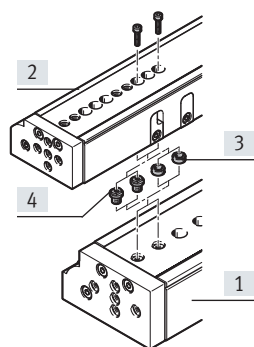
Datasheet

Possible combinations without adapter plate

Pick and place

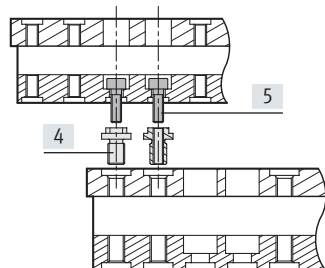


Piggy-back assembly



- [3] Centring sleeve ZBH
[4] Connector sleeve ZBV

Mounting example with connector sleeve ZBV



- [4] Connector sleeve ZBV2)
[5] Screw

		[1] Base drive								
		Size	4	6	8	10	12	16	20	25
[2] Assembly drive	4	2x M3x7 2x ZBH-5 ¹⁾	2x M3x10 2x ZBH-5 ¹⁾	ZBV-M4-7 ²⁾	ZBV-M4-7 ²⁾	–	–	–	–	
	6	–	2x M3x10 2x ZBH-5 ¹⁾	ZBV-M4-7 ²⁾	ZBV-M4-7 ²⁾	–	–	–	–	
	8	–	–	2x M4x12 2x ZBH-7 ¹⁾	2x M4x12 2x ZBH-7 ¹⁾	ZBV-M5-7 ²⁾	ZBV-M5-7 ²⁾	–	–	
	10	–	–	–	2x M4x14 2x ZBH-7 ¹⁾	ZBV-M5-7 ²⁾	ZBV-M5-7 ²⁾	–	–	
	12	–	–	–	–	2x M5x14 2x ZBH-7 ¹⁾	2x M5x16 2x ZBH-7 ¹⁾	ZBV-M6-9 ²⁾	ZBV-M6-9 ²⁾	
	16	–	–	–	–	–	2x M5x18 2x ZBH-7 ¹⁾	ZBV-M6-9 ²⁾	ZBV-M6-9 ²⁾	
	20	–	–	–	–	–	–	2x M6x20 2x ZBH-9 ¹⁾	2x M6x20 2x ZBH-9 ¹⁾	
	25	–	–	–	–	–	–	–	2x M6x30 2x ZBH-9 ¹⁾	

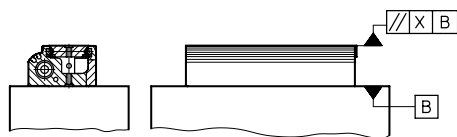
1) Centring sleeves ZBH are included in the scope of delivery of the mini slide DGSL

2) Connector sleeves ZBV → Page 52

Datasheet

Parallelism [mm]

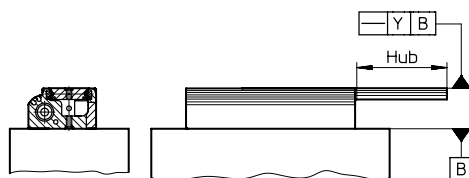
The term parallelism refers to the alignment accuracy between the mounting surface and the slide surface.



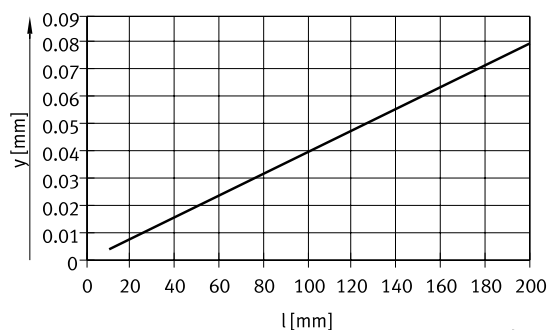
Size	Stroke [mm]	4	6	8	10	12	16	20	25
Parallelism X	10	0.02	0.02	0.02	0.02	0.02	0.02	0.02	0.02
	20	0.02	0.02	0.02	0.02	0.025	0.025	0.025	0.025
	30	0.025	0.025	0.025	0.025	0.025	0.025	0.03	0.03
	40	–	0.025	0.025	0.025	0.03	0.03	0.035	0.035
	50	–	0.03	0.03	0.03	0.035	0.035	0.04	0.04
	80	–	–	0.035	0.035	0.04	0.04	0.045	0.045
	100	–	–	–	0.045	0.05	0.05	0.055	0.055
	150	–	–	–	–	0.075	0.075	0.08	0.08
	200	–	–	–	–	–	–	0.08	0.08

Linearity [mm]

The term linearity refers to the alignment accuracy between the mounting surface and the slide surface as a function of the stroke.



Linear travel accuracy y as a function of stroke length l



Datasheet

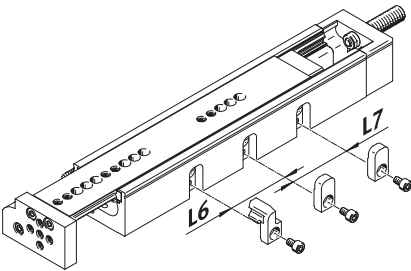
Adjustable end-position range
Rough adjustment of the front end position

With the mini slide DGSL, the advanced fixed stop can be relocated by swapping it with the cover.
This permits a stroke reduction down to the next but one smaller standard stroke through a combination of rough and precision adjustments.

- Advantages:
- Can be flexibly adapted to the application
 - Integrated, which means reduced conversion effort and costs
 - Large adjustment range

**Note**

Removal of the fixed stops can severely damage the mini slide DGSL.



Size Stroke [mm]	4		6		8		10		12		16		20		25	
	L6	L7	L6	L7	L6	L7	L6	L7	L6	L7	L6	L7	L6	L7	L6	L7
10	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
20	10	–	14	–	10	–	–	–	–	–	–	–	–	–	–	–
30	10	–	14	–	16	–	–	–	–	–	–	–	–	–	–	–
40	–	–	14	–	16	–	–	–	–	–	–	–	–	–	–	–
50	–	–	14	14	16	–	–	–	–	–	–	–	–	–	–	–
80	–	–	–	–	16	16	24	–	29	–	35	–	–	–	55	–
100	–	–	–	–	–	–	24	24	29	–	35	–	44	–	55	–
150	–	–	–	–	–	–	–	–	29	29	35	–	44	–	55	–
200	–	–	–	–	–	–	–	–	–	–	–	–	44	44	55	–

Example:
DGSL-12-150-...
Max. stroke = 150 mm

By repositioning the fixed stop by the dimension L6:
Stroke = 150 – 29 = 121 mm

By repositioning the fixed stop by the dimension L6 and L7:
Stroke = 150 – 29 – 29 = 92 mm

In addition, the stroke can be reduced through a precision adjustment:
Stroke = 150 – 29 – 29 – 29
= 63 mm

Precision adjustment of the advanced and retracted end position →
Page 11

Datasheet

Adjustable end-position range

Precision adjustment of the advanced and retracted end position

Precision adjustment of the required stroke reduction is possible using the cushioning components (on the slide and in the end cap).

Advantages:

- Precision adjustment is accurately fixed by the clamping component
- No readjustment required, position is fully retained under lock and load

- Quick and easy adjustment, only one tool required

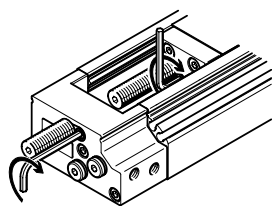
Step 1:
Loosen the clamping component

Step 2:
Position the slide by hand in the required end position

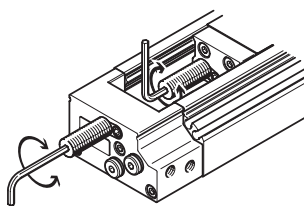
Step 3:
Turn the stop element with an Allen key until the end position is reached.

Step 4:
Tighten the clamping component

Step 1



Step 2 ... 4



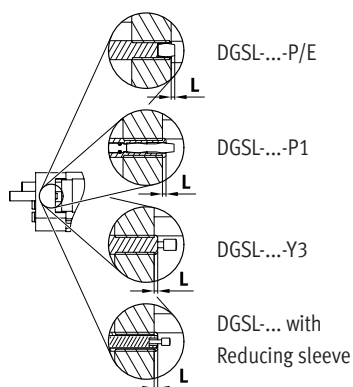
Adjustable end position range [mm] per end position / stroke reduction

Size		4	6	8	10	12	16	20	25
Front end position									
With cushioning	P	-14.5	-16.5	-19.5	-27.5	-29	-37.5	-50.5	-55
	E	-4.5	-5	-4.5	-13	-9	-3.5	-6.5	-11.5
	P1	-14.5	-16.5	-19.5	-27.5	-29	-37.5	-50.5	-55
	Y3	-	-	-15	-24	-29	-36.5	-44	-56
	1)	-	-	-	-24	-29	-36.5	-44	-56
Rear end position									
With cushioning	P	-13.5	-15	-18.5	-20	-25.5	-39.5	-49.5	-49
	E	-3.5	-3.5	-3.5	-5.5	-5.5	-5.5	-5.5	-5.5
	P1	-13.5	-15	-18.5	-20	-25.5	-39.5	-49.5	-49
	Y3	-	-	-14	-15	-25.5	-38.5	-42	-51.5
	1)	-	-	-	-15	-25.5	-38.5	-42	-51.5

1) With reducing sleeve and next smaller shock absorber.

 **Note**

The distance L of the cushioning element (→ operating manual) must be maintained at all times (factory setting).



 **Note**

The adjustment range of the advanced and retracted end position is restricted when using the cushioning type "E".

Datasheet

Shock absorber selection

Payload load m as a function of impact velocity v

With the mini slide DGSL, shock absorbers can be replaced and the cushioning behaviour can thus be influenced (depending on the payload).

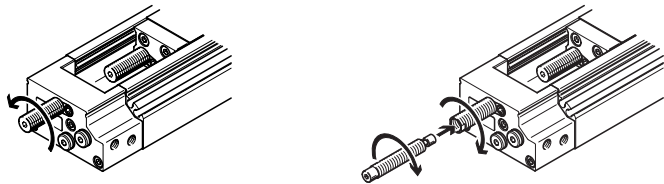
This is done by removing the existing shock absorbers on the DGSL and replacing them with a smaller shock absorber as appropriate to the application.
(→ description below)

Graphs
For selecting a suitable shock absorber as a function of the mounting position of the mini slide
→ from page 13

Ordering data
Shock absorbers DYSW, DYEF and reducing sleeve DAYH
→ Page 51

For smaller loads:

The next smaller shock absorber DYSW can be installed with the help of the reducing sleeve DAYH.



For very small loads:

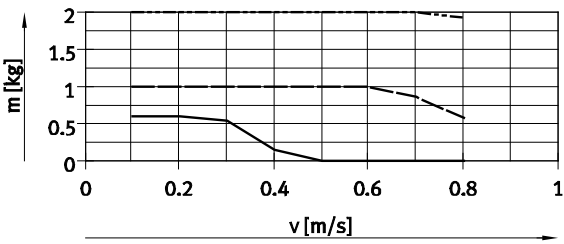
The shock absorber DYEF can be installed.



Selection example:

Current drive:
Mini slide: DGSL-10-...-Y3-A

Where:
Payload: 500 g
Impact velocity: 0.4 m/s
Mounting position: horizontal



- DYSW-5-8 (cushioning Y3)
- DYSW-4-6 with DAYH-4 (cushioning Y11)
- DYEF-M8-Y1F

Results:
The first cushioning curve, which is positioned above the intersection point, is the most suitable for this case.
To improve the cushioning characteristics when the payload is of less than one kilogram, replace the shock absorber DYSW-5-8 integrated in the mini slide with the reducing sleeve DAYH-4 and the next smaller shock absorber DYSW-4-6.

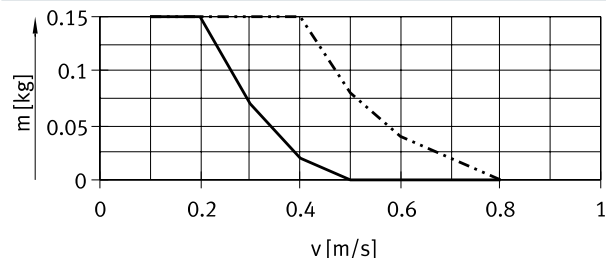
Basically, shock absorbers must be loaded.
Since the shock absorber DYSW-4-6 is more fully utilised in this case, both the service life of the shock absorber and the cushioning characteristics are improved.

Datasheet

Shock absorber selection

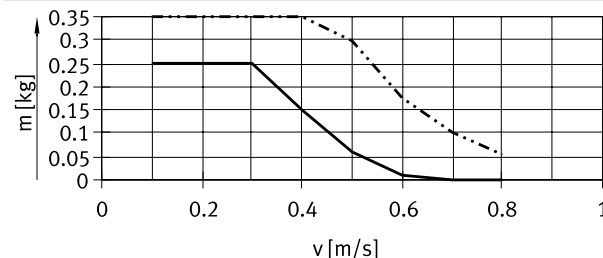
Payload m as a function of impact velocity v – horizontal mounting position

DGSL-4



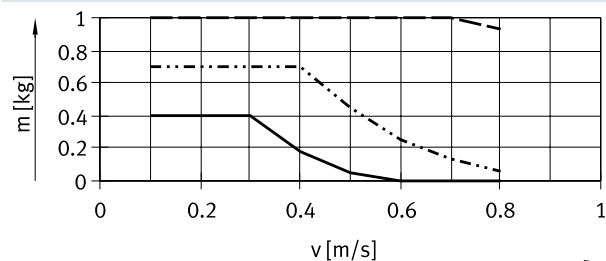
- DYEF-M4-Y1F (cushioning P1)
 DYEF-M4-Y1 (cushioning P)

DGSL-6



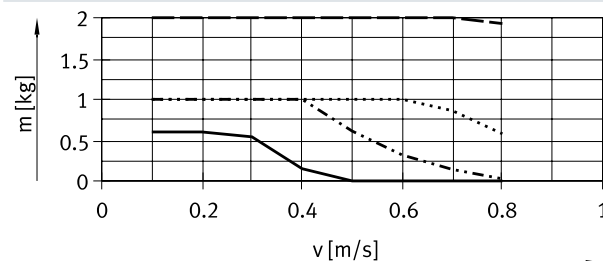
- DYEF-M5-Y1F (cushioning P1)
 DYEF-M5-Y1 (cushioning P)

DGSL-8



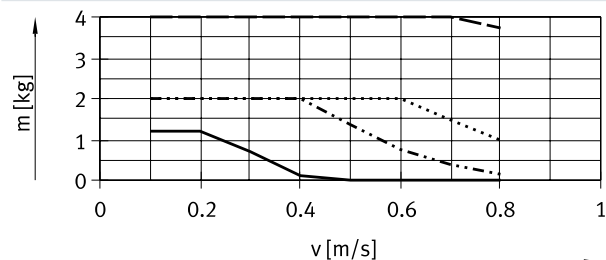
- DYEF-M6-Y1F (cushioning P1)
 DYEF-M6-Y1 (cushioning P)
 --- DYSW-4-6 (cushioning Y3)

DGSL-10



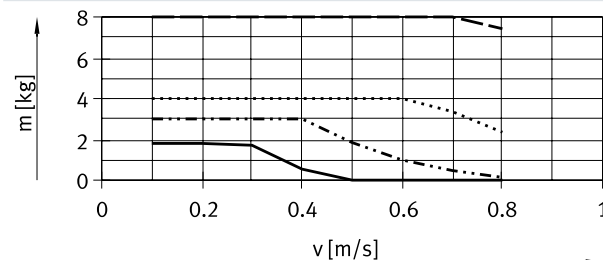
- DYEF-M8-Y1F (cushioning P1)
 DYEF-M8-Y1 (cushioning P)
 --- DYSW-5-8 (cushioning Y3)
 DYSW-4-6 with DAYH-4 (cushioning Y11)

DGSL-12



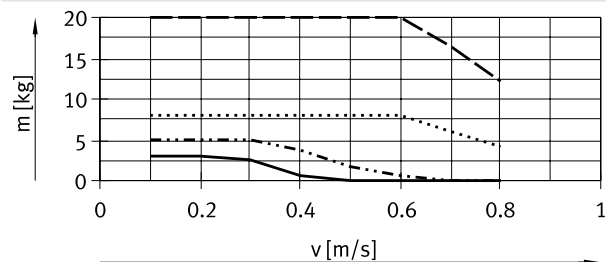
- DYEF-M10-Y1F (cushioning P1)
 DYEF-M10-Y1 (cushioning P)
 --- DYSW-7-10 (cushioning Y3)
 DYSW-5-8 with DAYH-5 (cushioning Y11)

DGSL-16



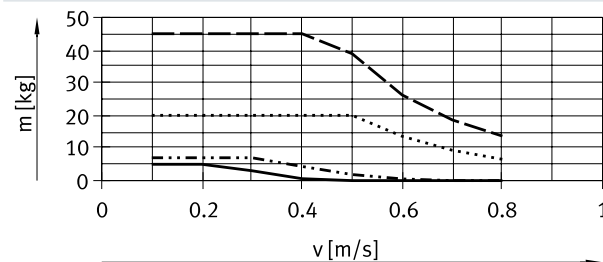
- DYEF-M12-Y1F (cushioning P1)
 DYEF-M12-Y1 (cushioning P)
 --- DYSW-8-14 (cushioning Y3)
 DYSW-7-10 with DAYH-7 (cushioning Y11)

DGSL-20



- DYEF-M14-Y1F (cushioning P1)
 DYEF-M14-Y1 (cushioning P)
 --- DYSW-10-17 (cushioning Y3)
 DYSW-8-14 with DAYH-8 (cushioning Y11)

DGSL-25



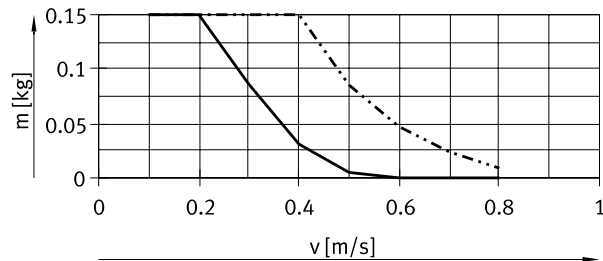
- DYEF-M16-Y1F (cushioning P1)
 DYEF-M16-Y1 (cushioning P)
 --- DYSW-12-20 (cushioning Y3)
 DYSW-10-17 with DAYH-10 (cushioning Y11)

Datasheet

Shock absorber selection

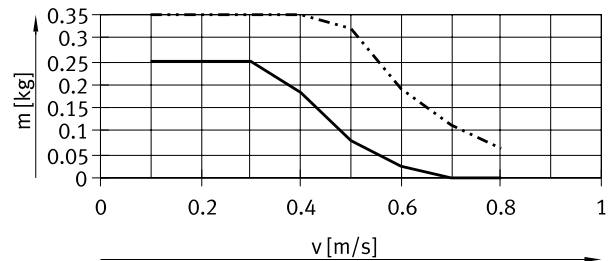
Payload m as a function of impact velocity v – vertical mounting position, payload moving upwards

DGSL-4



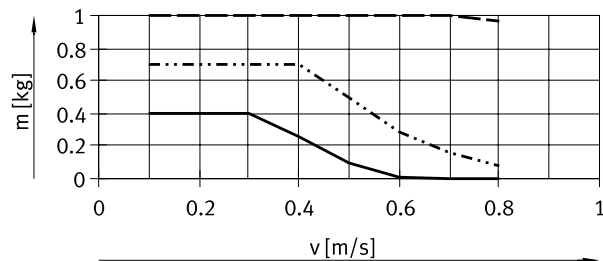
- DYEF-M4-Y1F (cushioning P1)
- · - · - DYEF-M4-Y1 (cushioning P)

DGSL-6



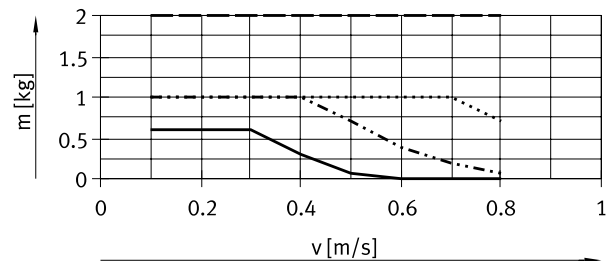
- DYEF-M5-Y1F (cushioning P1)
- · - · - DYEF-M5-Y1 (cushioning P)

DGSL-8



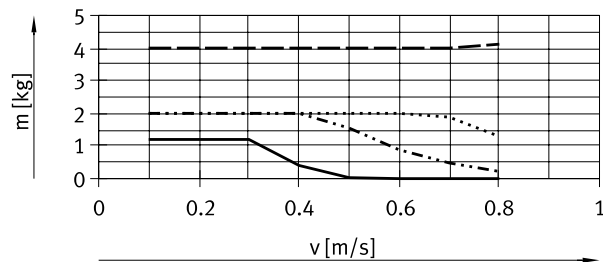
- DYEF-M6-Y1F (cushioning P1)
- · - · - DYEF-M6-Y1 (cushioning P)
- - - - - DYSW-4-6 (cushioning Y3)

DGSL-10



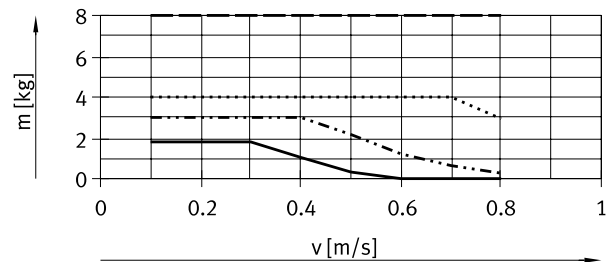
- DYEF-M8-Y1F (cushioning P1)
- · - · - DYEF-M8-Y1 (cushioning P)
- - - - - DYSW-5-8 (cushioning Y3)
- DYSW-4-6 with DAYH-4 (cushioning Y11)

DGSL-12



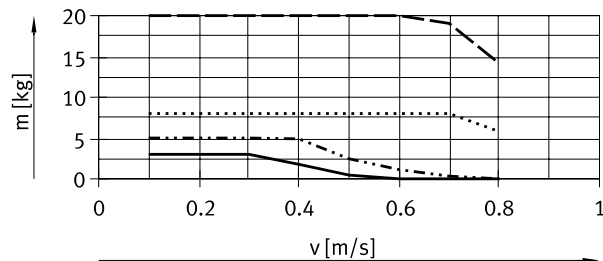
- DYEF-M10-Y1F (cushioning P1)
- · - · - DYEF-M10-Y1 (cushioning P)
- - - - - DYSW-7-10 (cushioning Y3)
- DYSW-5-8 with DAYH-5 (cushioning Y11)

DGSL-16



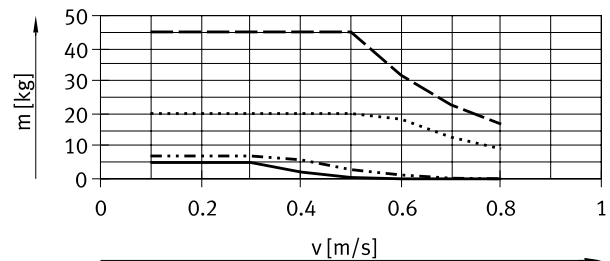
- DYEF-M12-Y1F (cushioning P1)
- · - · - DYEF-M12-Y1 (cushioning P)
- - - - - DYSW-8-14 (cushioning Y3)
- DYSW-7-10 with DAYH-7 (cushioning Y11)

DGSL-20



- DYEF-M14-Y1F (cushioning P1)
- · - · - DYEF-M14-Y1 (cushioning P)
- - - - - DYSW-10-17 (cushioning Y3)
- DYSW-8-14 with DAYH-8 (cushioning Y11)

DGSL-25



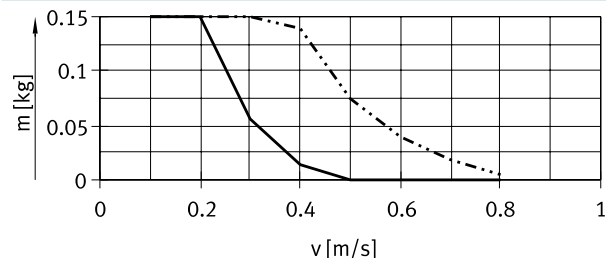
- DYEF-M16-Y1F (cushioning P1)
- · - · - DYEF-M16-Y1 (cushioning P)
- - - - - DYSW-12-20 (cushioning Y3)
- DYSW-10-17 with DAYH-10 (cushioning Y11)

Datasheet

Shock absorber selection

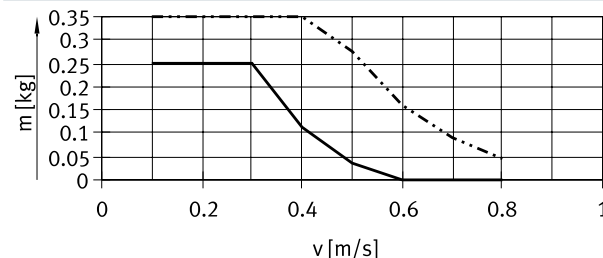
Payload m as a function of impact velocity v – vertical mounting position, payload moving downwards

DGSL-4



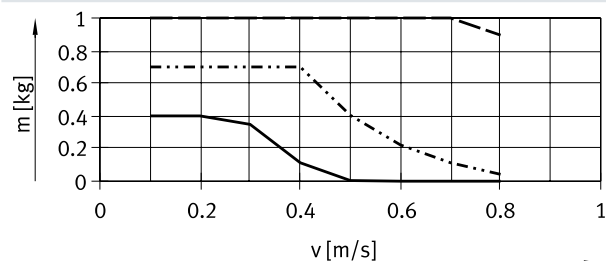
- DYEF-M4-Y1F (cushioning P1)
 DYEF-M4-Y1 (cushioning P)

DGSL-6



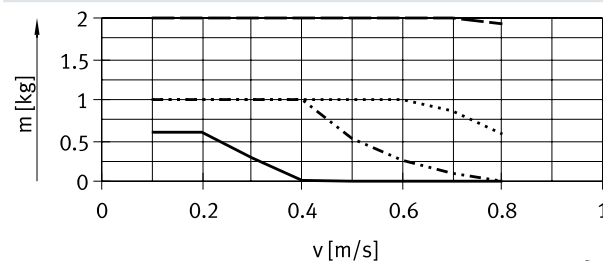
- DYEF-M5-Y1F (cushioning P1)
 DYEF-M5-Y1 (cushioning P)

DGSL-8



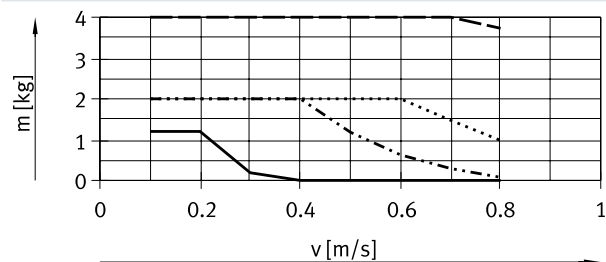
- DYEF-M6-Y1F (cushioning P1)
 DYEF-M6-Y1 (cushioning P)
 - - - - - DYSW-4-6 (cushioning Y3)

DGSL-10



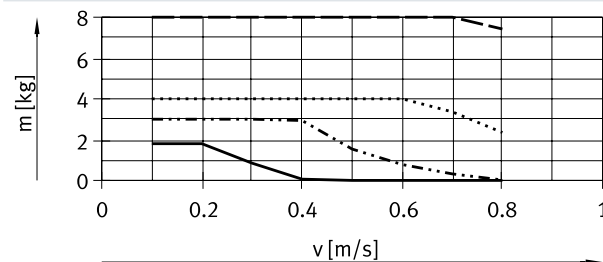
- DYEF-M8-Y1F (cushioning P1)
 DYEF-M8-Y1 (cushioning P)
 - - - - - DYSW-5-8 (cushioning Y3)
 DYSW-4-6 with DAYH-4 (cushioning Y11)

DGSL-12



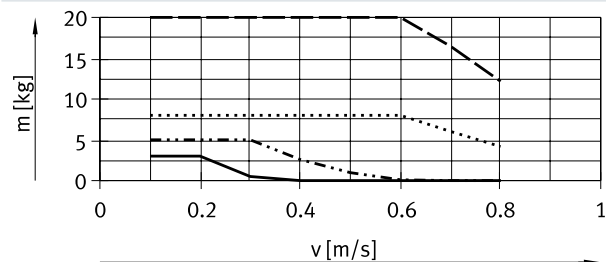
- DYEF-M10-Y1F (cushioning P1)
 DYEF-M10-Y1 (cushioning P)
 - - - - - DYSW-7-10 (cushioning Y3)
 DYSW-5-8 with DAYH-5 (cushioning Y11)

DGSL-16



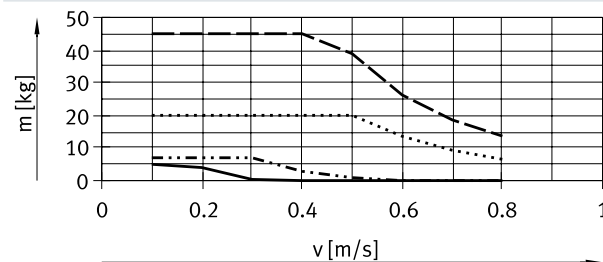
- DYEF-M12-Y1F (cushioning P1)
 DYEF-M12-Y1 (cushioning P)
 - - - - - DYSW-8-14 (cushioning Y3)
 DYSW-7-10 with DAYH-7 (cushioning Y11)

DGSL-20



- DYEF-M14-Y1F (cushioning P1)
 DYEF-M14-Y1 (cushioning P)
 - - - - - DYSW-10-17 (cushioning Y3)
 DYSW-8-14 with DAYH-8 (cushioning Y11)

DGSL-25

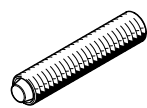


- DYEF-M16-Y1F (cushioning P1)
 DYEF-M16-Y1 (cushioning P)
 - - - - - DYSW-12-20 (cushioning Y3)
 DYSW-10-17 with DAYH-10 (cushioning Y11)

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P/E – horizontal mounting position

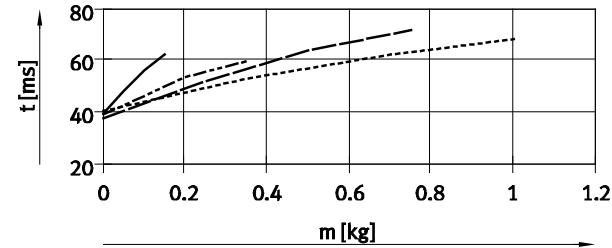


The values in the graphs are determined by calculation.
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position
→ Page 19

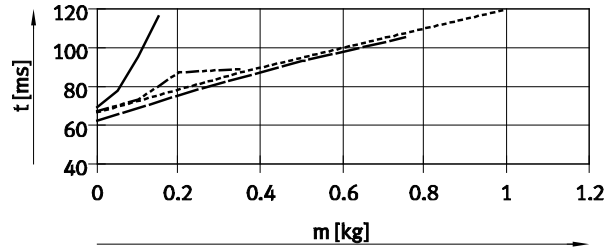
Advancing

Stroke 10 mm, size 4 ... 10

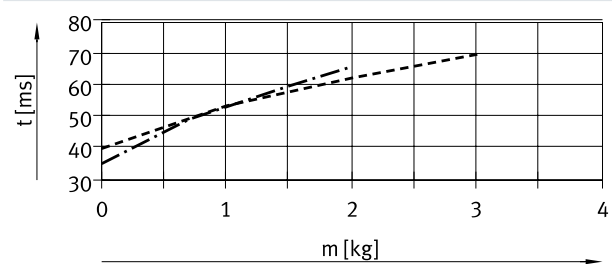


Retracting

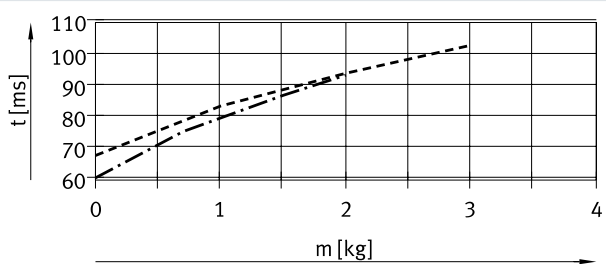
Stroke 10 mm, size 4 ... 10



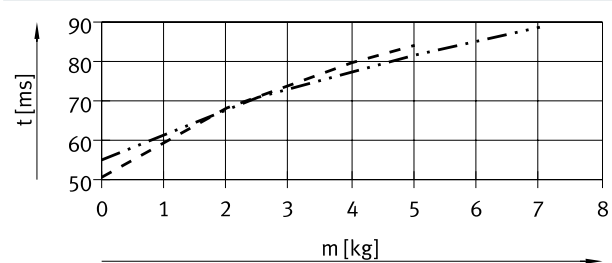
Stroke 10 mm, size 12 ... 16



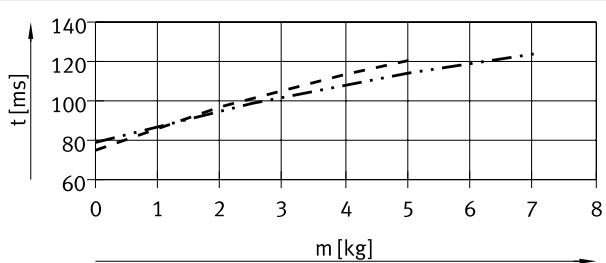
Stroke 10 mm, size 12 ... 16



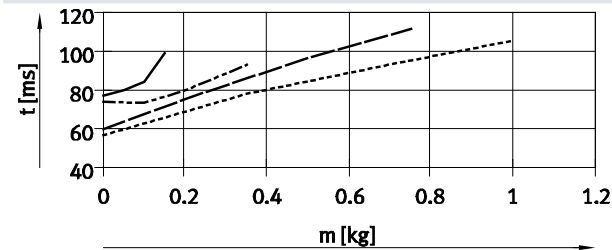
Stroke 10 mm, size 20 ... 25



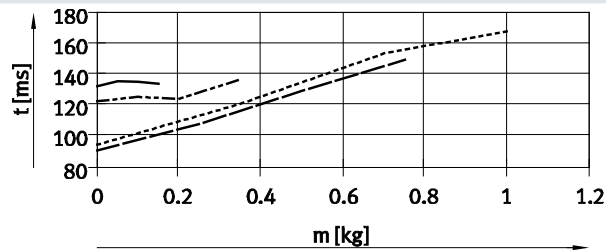
Stroke 10 mm, size 20 ... 25



Stroke 30 mm, size 4 ... 10



Stroke 30 mm, size 4 ... 10

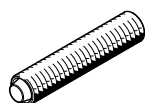


- DGSL-4
- · - · - DGSL-6
- - - - DGSL-8
- DGSL-10
- · - · - DGSL-12
- - - - DGSL-16
- - - - DGSL-20
- · - · - DGSL-25

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P/E – horizontal mounting position



The values in the graphs are determined by calculation.

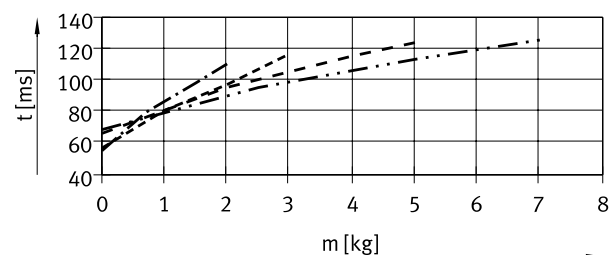
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position

→ Page 19

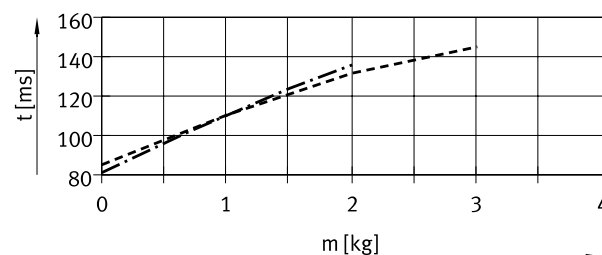
Advancing

Stroke 30 mm, size 12 ... 25

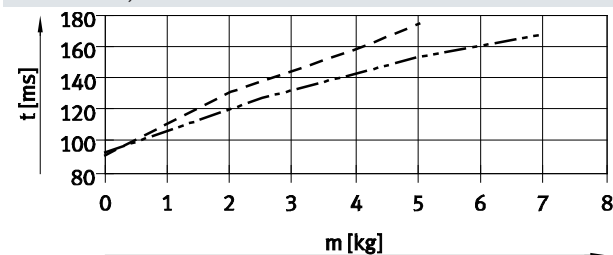


Retracting

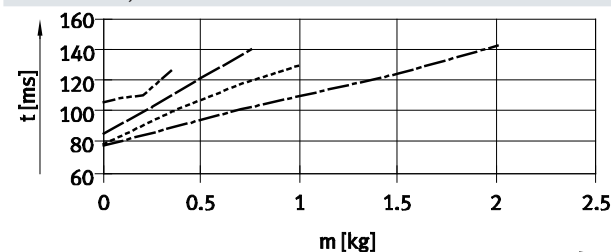
Stroke 30 mm, size 12 ... 16



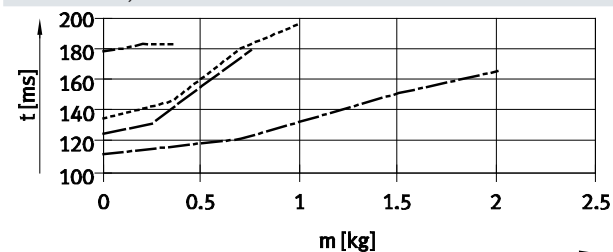
Stroke 30 mm, size 20 ... 25



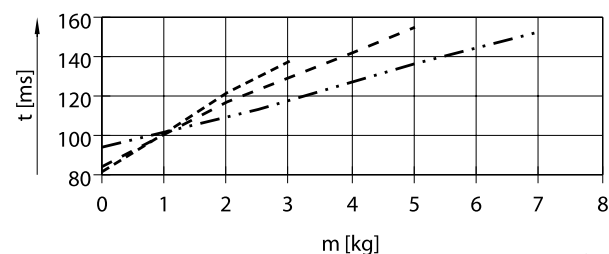
Stroke 50 mm, size 6 ... 12



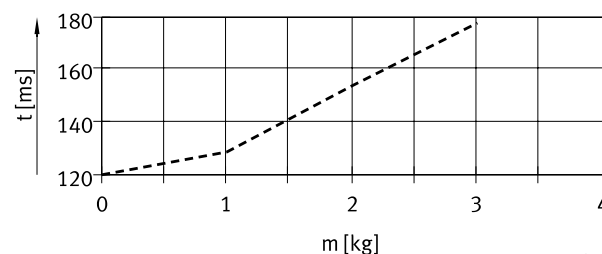
Stroke 50 mm, size 6 ... 12



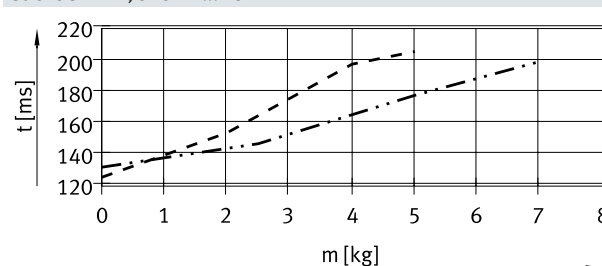
Stroke 50 mm, size 16 ... 25



Stroke 50 mm, size 16



Stroke 50 mm, size 20 ... 25



Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P/E – horizontal mounting position



The values in the graphs are determined by calculation.

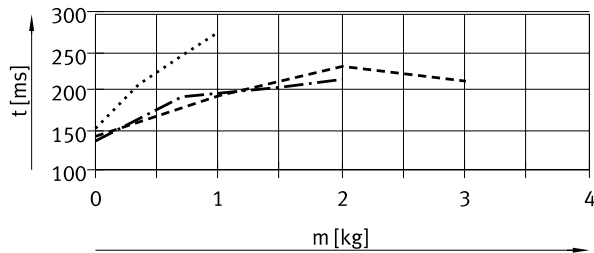
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position

→ Page 19

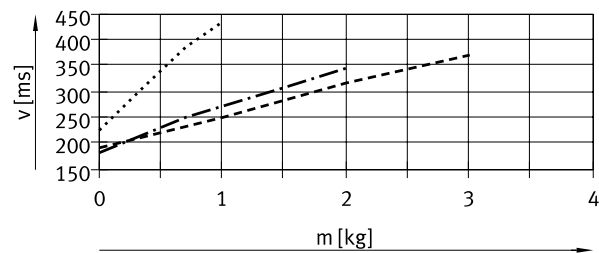
Advancing

Stroke 100 mm, size 10 ... 16

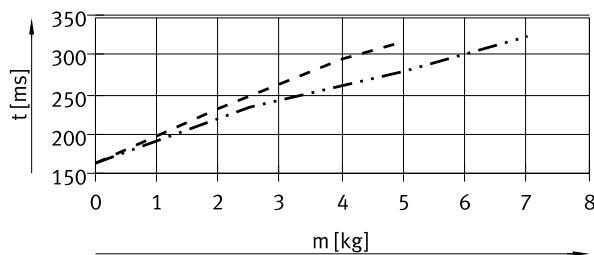


Retracting

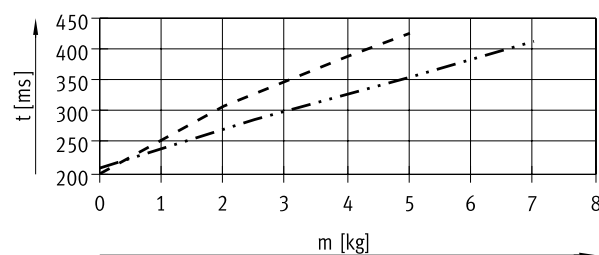
Stroke 100 mm, size 10 ... 16



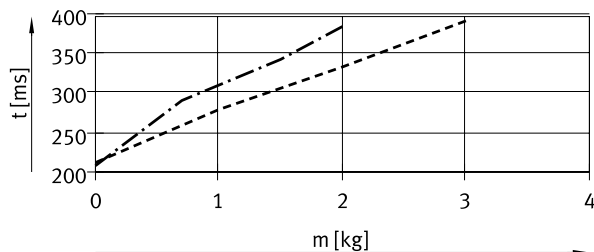
Stroke 100 mm, size 20 ... 25



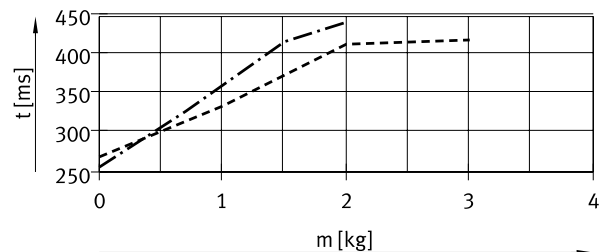
Stroke 100 mm, size 20 ... 25



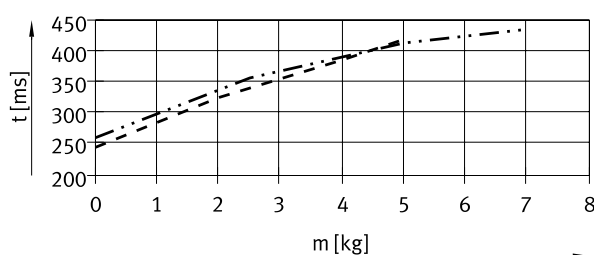
Stroke 150 mm, size 12 ... 16



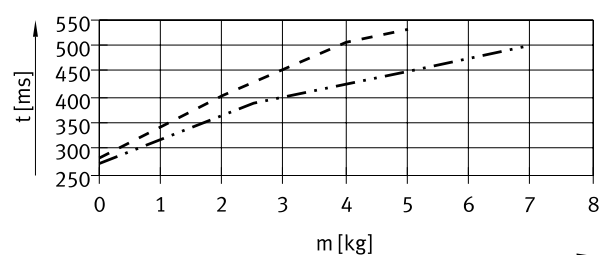
Stroke 150 mm, size 12 ... 16



Stroke 150 mm, size 20 ... 25



Stroke 150 mm, size 20 ... 25

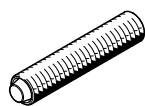


- DGSL-10
- · - · - DGSL-12
- - - - - DGSL-16
- - - - - DGSL-20
- · - · - DGSL-25

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P/E – horizontal mounting position



The values in the graphs are determined by calculation.

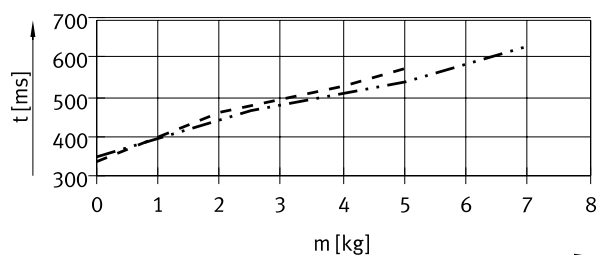
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position

→ Page 19

Advancing

Stroke 200 mm, size 20 ... 25

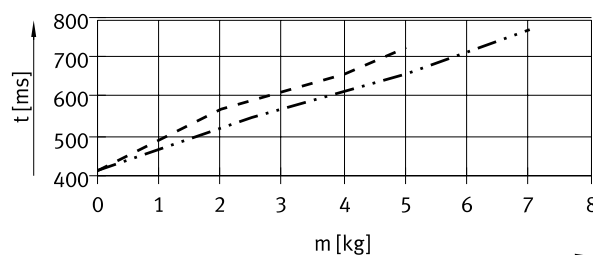


--- DGSL-20

- . - DGSL-25

Retracting

Stroke 200 mm, size 20 ... 25



Vertical mounting position

The travel times for a vertical mounting position are calculated by multiplying the data for a horizontal mounting position by a correction factor k_a (advancing) and k_r (retracting), see adjacent table.

Where:

Stroke = 200 mm

Size = 20

Payload = 3 kg

Calculated travel time t_h (horizontal),

see graph:

– Advancing = 500 ms

– Retracting = 600 ms

Calculated travel time t_v (vertical):

– Advancing: $t_v = t_h \times k_a$

$t_s = 500 \text{ ms} \times 0.9 = 450 \text{ ms}$

– Retracting: $t_v = t_h \times k_r$

$t_s = 600 \text{ ms} \times 1.1 = 660 \text{ ms}$

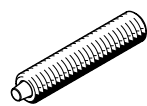
Stroke [mm]	Size	Advancing (k_a) 1)	Retracting (k_r)
10	4, 6, 8, 10	0.95	1.1
	12, 16, 20, 25	0.95	1.2
30	4, 6, 8, 10	0.95	1.1
	12, 16, 20, 25	0.95	1.2
50	6, 8, 10, 12	0.9	1.1
	16, 20, 25	1.1	1.2
100	10, 12, 16, 20, 25	1	1.1
150	12, 16, 20, 25	1	1.1
200	20, 25	0.9	1.1

1) Downward.

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P1 – horizontal mounting position

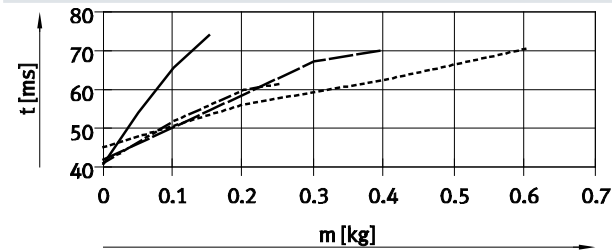


The values in the graphs are determined by calculation.
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position
→ Page 23

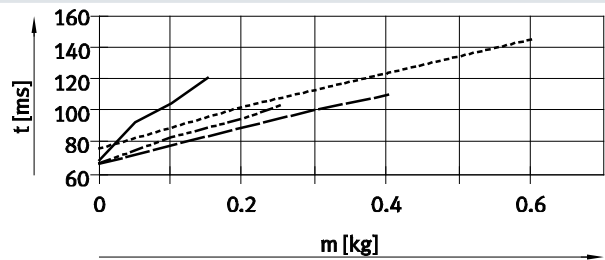
Advancing

Stroke 10 mm, size 4 ... 10

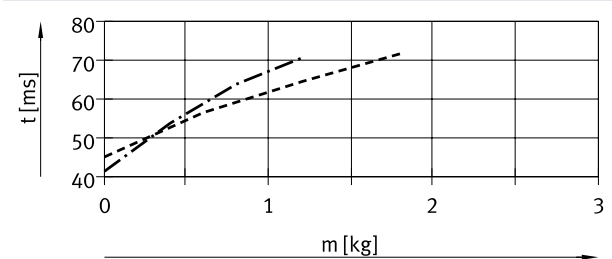


Retracting

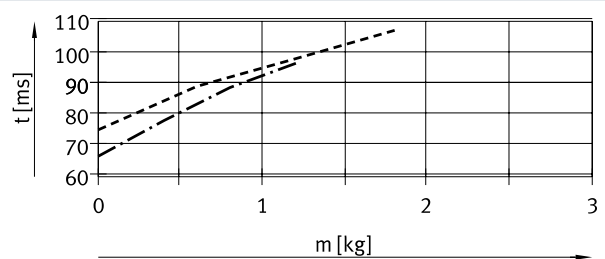
Stroke 10 mm, size 4 ... 10



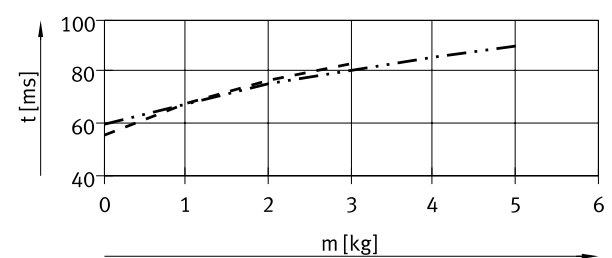
Stroke 10 mm, size 12 ... 16



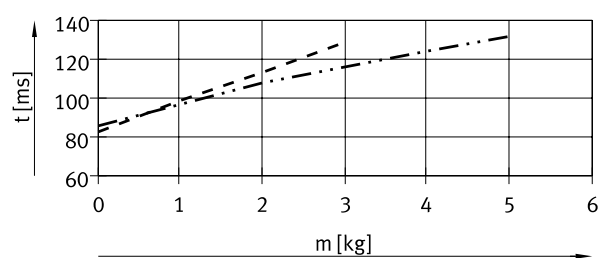
Stroke 10 mm, size 12 ... 16



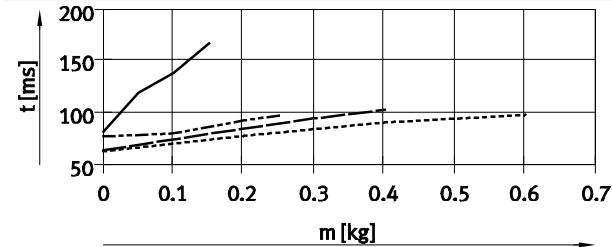
Stroke 10 mm, size 20 ... 25



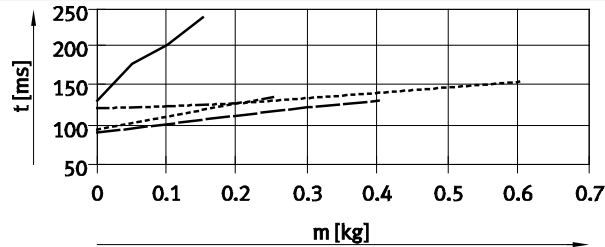
Stroke 10 mm, size 20 ... 25



Stroke 30 mm, size 4 ... 10



Stroke 30 mm, size 4 ... 10

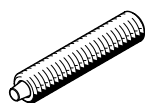


- DGSL-4
- DGSL-6
- DGSL-8
- DGSL-10
- DGSL-12
- DGSL-16
- DGSL-20
- DGSL-25

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P1 – horizontal mounting position



The values in the graphs are determined by calculation.

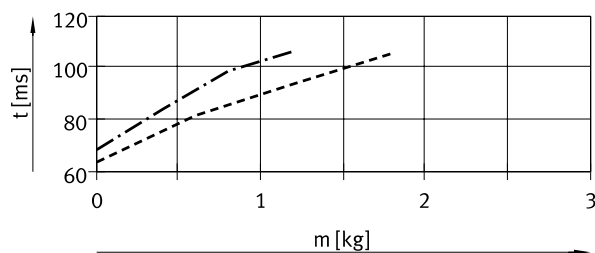
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position

→ Page 23

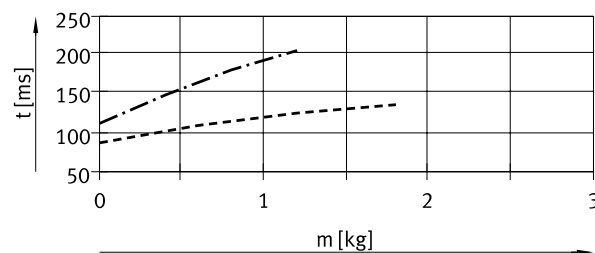
Advancing

Stroke 30 mm, size 12 ... 16

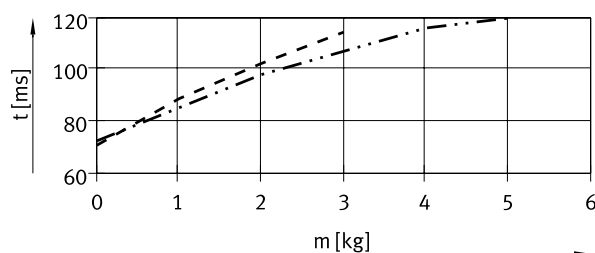


Retracting

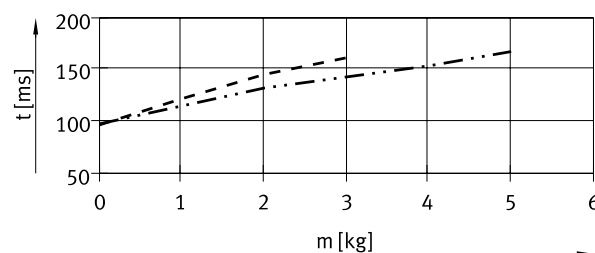
Stroke 30 mm, size 12 ... 16



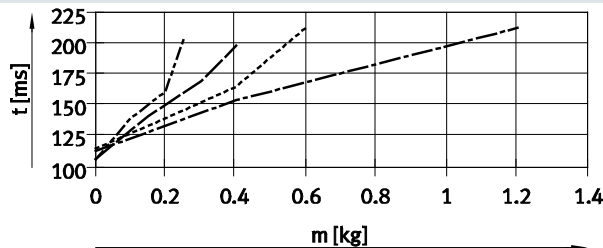
Stroke 30 mm, size 20 ... 25



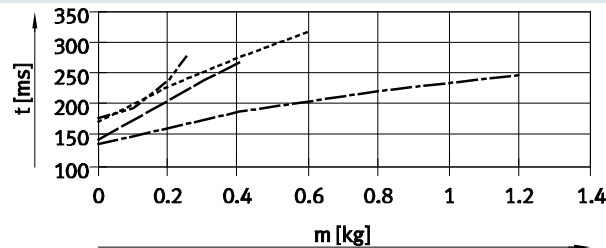
Stroke 30 mm, size 20 ... 25



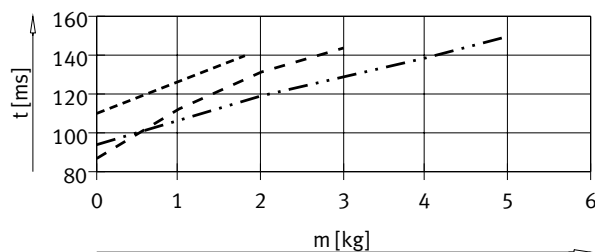
Stroke 50 mm, size 6 ... 12



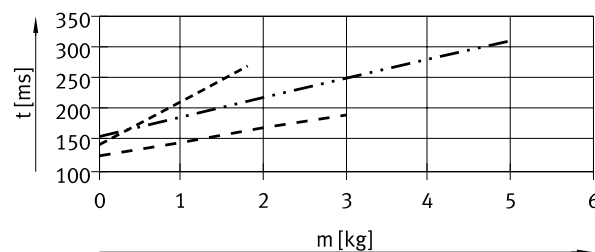
Stroke 50 mm, size 6 ... 12



Stroke 50 mm, size 16 ... 25



Stroke 50 mm, size 16 ... 25



..... DGSL-6

----- DGSL-8

..... DGSL-10

- . - . - DGSL-12

----- DGSL-16

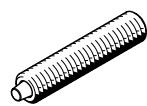
----- DGSL-20

- . - . - DGSL-25

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P1 – horizontal mounting position

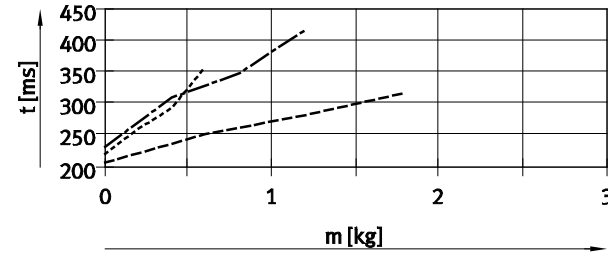


The values in the graphs are determined by calculation.
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

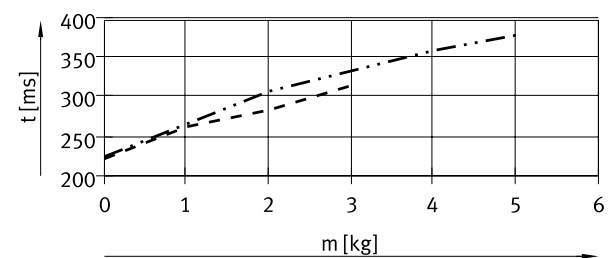
Vertical mounting position
→ Page 23

Advancing

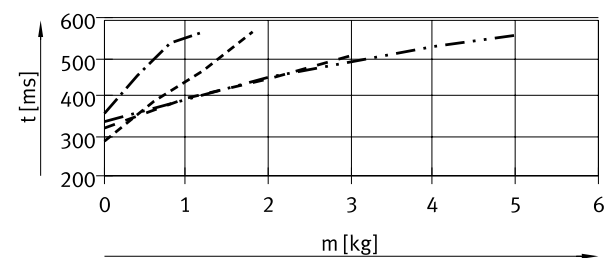
Stroke 100 mm, size 10 ... 16



Stroke 100 mm, size 20 ... 25



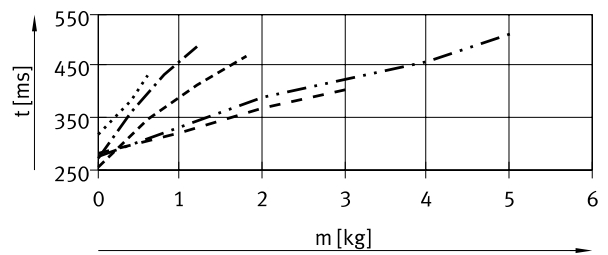
Stroke 150 mm, size 12 ... 25



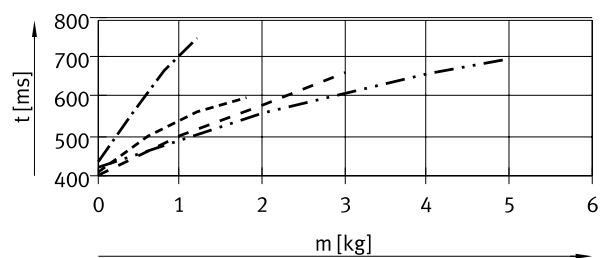
- DGSL-10
- . - . DGSL-12
- DGSL-16
- DGSL-20
- DGSL-25

Retracting

Stroke 100 mm, size 10 ... 25



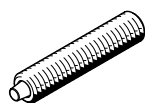
Stroke 150 mm, size 12 ... 25



Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning P1 – horizontal mounting position



The values in the graphs are determined by calculation.

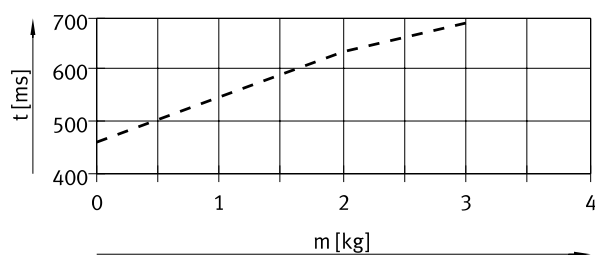
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position

→ Page 23

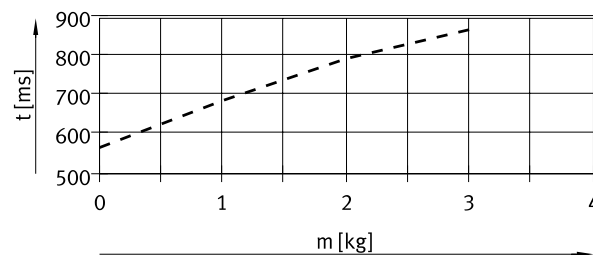
Advancing

Stroke 200 mm, size 20

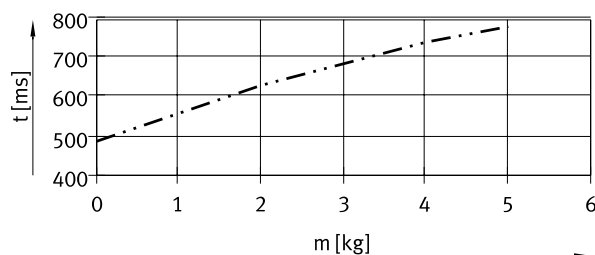


Retracting

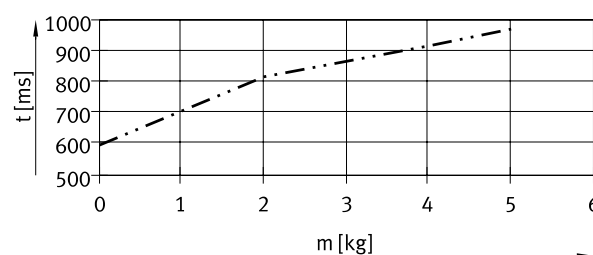
Stroke 200 mm, size 20



Stroke 200 mm, size 25



Stroke 200 mm, size 25



--- DGSL-20

- . - . DGSL-25

Vertical mounting position

The travel times for a vertical mounting position are calculated by multiplying the data for a horizontal mounting position by a correction factor k_a (advancing) and k_r (retracting), see adjacent table.

Where:

Stroke = 200 mm

Size = 20

Payload = 2 kg

Calculated travel time t_h (horizontal),

see graph:

– Advancing = 640 ms

– Retracting = 780 ms

Calculated travel time t_v (vertical):

– Advancing: $t_v = t_h \times k_a$

$t_s = 640 \text{ ms} \times 0.9 = 576 \text{ ms}$

– Retracting: $t_v = t_h \times k_r$

$t_s = 780 \text{ ms} \times 1.1 = 858 \text{ ms}$

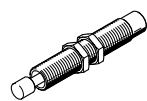
Stroke [mm]	Size	Advancing (k_a) 1)	Retracting (k_r)
10	4, 6, 8, 10	1	1.1
	12, 16, 20, 25	1.1	1.2
30	4, 6, 8, 10	1	1.1
	12, 16, 20, 25	1.1	1.2
50	6, 8, 10, 12	1	1.1
	16, 20, 25	0.9	1.1
100	10, 12, 16, 20, 25	0.95	1.1
150	12, 16, 20, 25	0.95	1.1
200	20, 25	0.9	1.1

1) Downward.

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning Y3 – horizontal mounting position

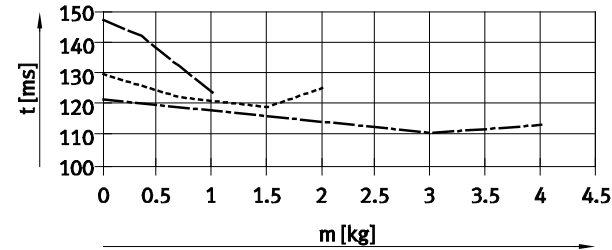


The values in the graphs are determined by calculation.
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position
→ Page 25

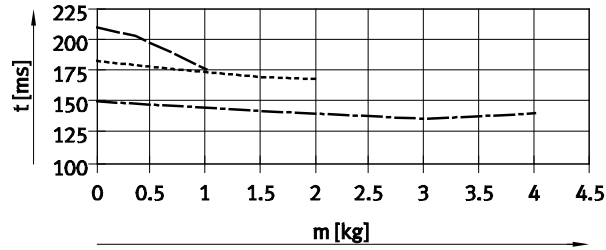
Advancing

Stroke 30 mm, size 8 ... 12

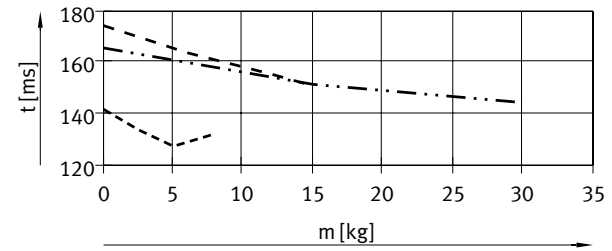


Retracting

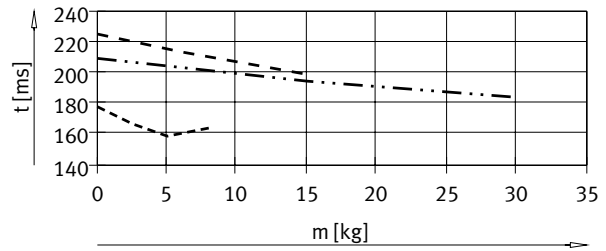
Stroke 30 mm, size 8 ... 12



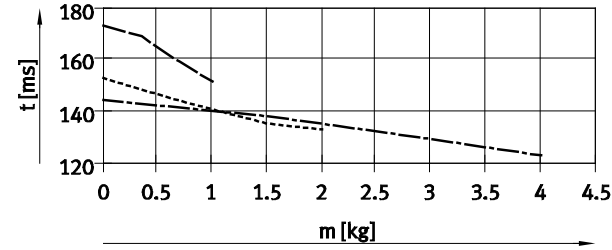
Stroke 30 mm, size 16 ... 25



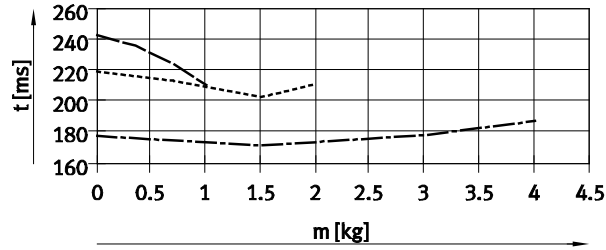
Stroke 30 mm, size 16 ... 25



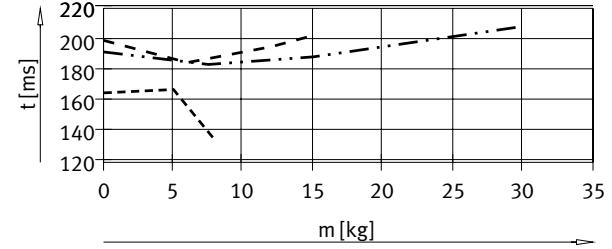
Stroke 50 mm, size 8 ... 12



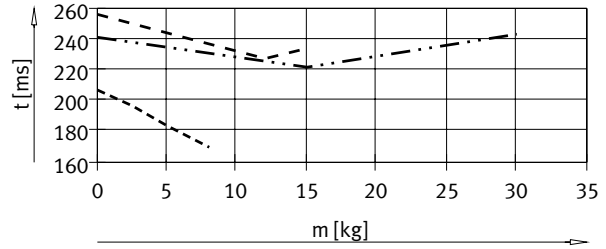
Stroke 50 mm, size 8 ... 12



Stroke 50 mm, size 16 ... 25



Stroke 50 mm, size 16 ... 25

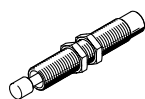


- DGSL-10
- - - - - DGSL-12
- . . . - DGSL-16
- - - - - DGSL-20
- . . . - DGSL-25

Datasheet

Shock absorber selection

Travel time t as a function of payload m and cushioning Y3 – horizontal mounting position



The values in the graphs are determined by calculation.

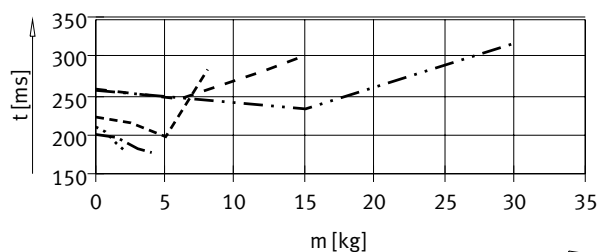
The travel time as a function of payload must not be reduced below the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position

→ Page 25

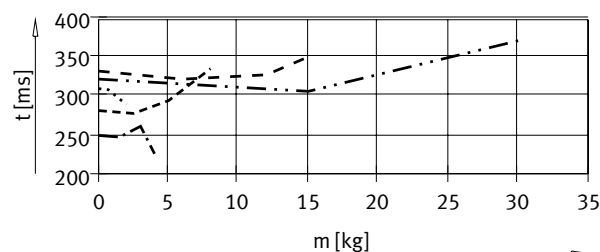
Advancing

Stroke 100 mm, size 10 ... 25

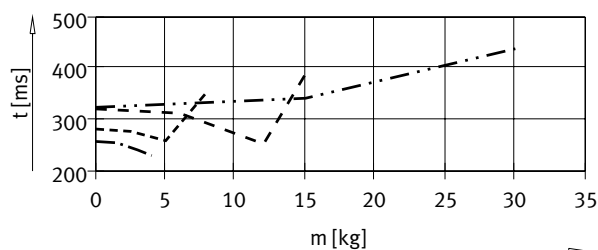


Retracting

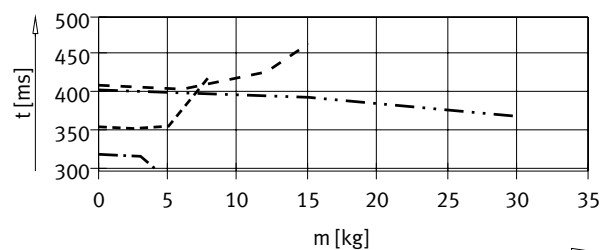
Stroke 100 mm, size 10 ... 25



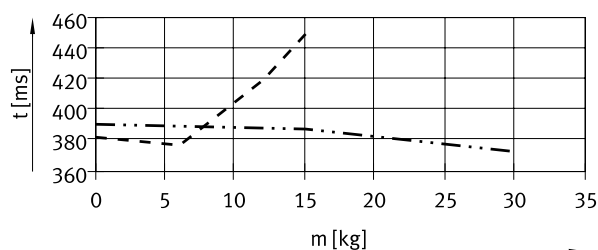
Stroke 150 mm, size 12 ... 25



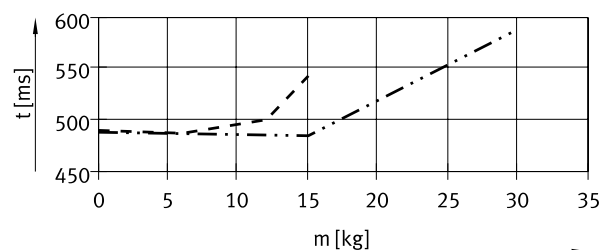
Stroke 150 mm, size 12 ... 25



Stroke 200 mm, size 20 ... 25



Stroke 200 mm, size 20 ... 25



--- DGSL-20

-.- DGSL-25

Vertical mounting position

The travel times for a vertical mounting position are calculated by multiplying the data for a horizontal mounting position by a correction factor k_a (advancing) and k_e (retracting), see adjacent table.

Where:

Stroke = 200 mm

Size = 20

Payload = 10 kg

Calculated travel time t_h (horizontal),

see graph:

– Advancing = 405 ms

– Retracting = 490 ms

Calculated travel time t_v

(vertical):

– Advancing: $t_v = t_h \times k_a$

$t_s = 405 \text{ ms} \times 0.9 = 365 \text{ ms}$

– Retracting: $t_v = t_h \times k_e$

$t_s = 490 \text{ ms} \times 1.5 = 735 \text{ ms}$

Stroke [mm]	Size	Advancing (k_a) 1)	Retracting (k_r)
30	8, 10, 12	0.95	1.2
	16, 20, 25	0.9	1.5
50	8, 10, 12	0.9	1.5
	16, 20, 25	0.9	1.5
100	10, 12, 16, 20, 25	0.8	1.5
150	12, 16, 20, 25	0.9	1.5
200	20, 25	0.9	1.5

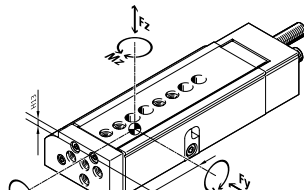
1) Downward.

Datasheet

Dynamic load values

The indicated torques refer to the centre of the guide.

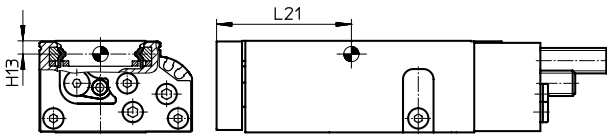
These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



If the drive is simultaneously subjected to several of the forces and torques indicated below, the following equation must be satisfied in addition to the indicated maximum loads:

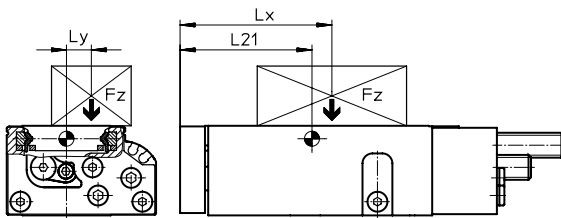
$$+ \frac{7,848 \text{ N}}{1200 \text{ N}} + \frac{0,236 \text{ Nm}}{18 \text{ Nm}} + \frac{0,886 \text{ Nm}}{12 \text{ Nm}} + 0 \leq 1$$

Position of the guide centre



Calculation example

Where:



Mini slide = DGSL-10

Stroke length

80 mm

Lever arm L_x = 50 mm

Lever arm L_y = 30 mm

Masse F_z = 0.8 kg

Acceleration a = 0 m/s²

To be determined:

F_y , F_z , M_x , M_y , M_z

and

Functional operation with combined load

Solution:

L_{21} = 83 mm from table

F_y = 0 N

F_z = $m \times g$

= 0.8 kg $\times$ 9.81 m/s² = 7.848 N

M_x = $m \times g \times L_y$

= 0.8 kg $\times$ 9.81 m/s² $\times$ 30 mm = 0.236 Nm

M_y = $m \times g \times [(L_{21} + \text{Hub}) - L_x]$

= 0.8 kg $\times$ 9.81 m/s² $\times$ [(83 mm + 80 mm) - 50 mm] = 0.886 Nm

M_z = 0 Nm

Combined load:

$$+ \frac{7,848 \text{ N}}{1200 \text{ N}} + \frac{0,236 \text{ Nm}}{18 \text{ Nm}} + \frac{0,886 \text{ Nm}}{12 \text{ Nm}} + 0 \leq 1$$

$$0 + \frac{7,848 \text{ N}}{1200 \text{ N}} + \frac{0,236 \text{ Nm}}{18 \text{ Nm}} + \frac{0,886 \text{ Nm}}{12 \text{ Nm}} + 0 \leq 1$$

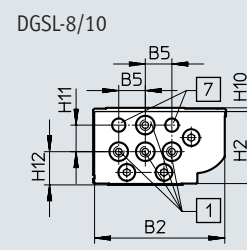
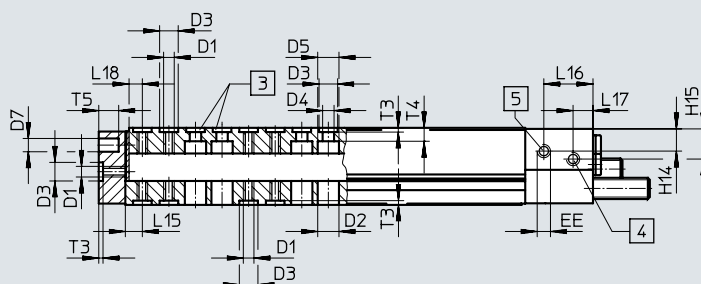
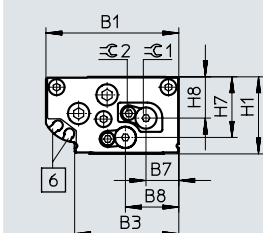
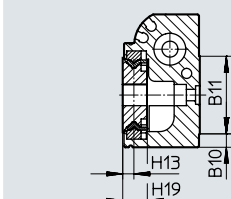
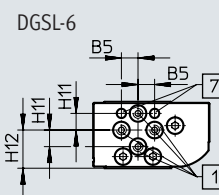
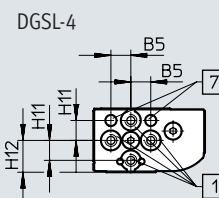
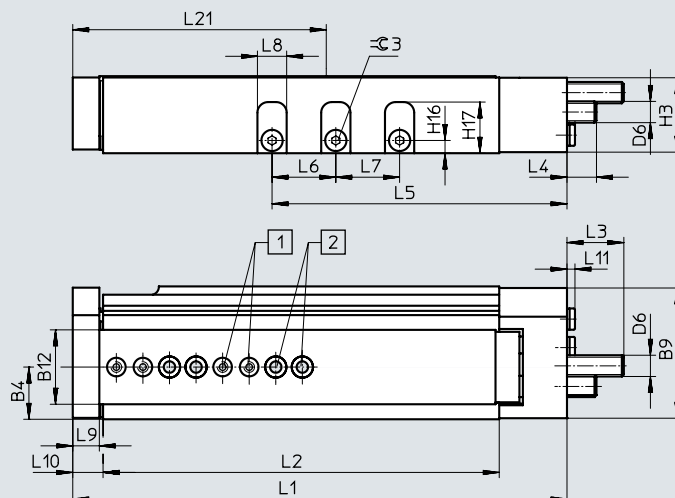
Permissible forces and torques						Geometric characteristics	
Size	Stroke [mm]	$F_{y_{\max}}$ [N]	$F_{z_{\max}}$ [N]	$M_{x_{\max}}$ [Nm]	$M_{y_{\max}}, M_{z_{\max}}$ [Nm]	H13 [mm]	L21 [mm]
4	10	343	343	2	2	2.7	31
	20	368	368	2	2		36
	30	387	387	2	2		42
6	10	540	540	6	4.5	3.4	37
	20	590	590	7	5		42
	30	631	631	8	5.5		47
	40	677	677	8	5.5		52
	50	719	719	8	5.5		57

Datasheet

Permissible forces and torques						Geometric characteristics	
Size	Stroke [mm]	F _y _{max} [N]	F _z _{max} [N]	M _x _{max} [Nm]	M _y _{max} , M _z _{max} [Nm]	H13 [mm]	L21 [mm]
8							
	10	657	657	7	5.5	3.25	41
	20	745	745	8	5.5		46
	30	850	850	9	5.5		51
	40	934	934	10	5.5		56
	50	962	962	10	8		67
	80	971	971	10	8		82
10							
	10	927	927	15	6	4.2	43
	20	1003	1003	15	7		46
	30	1078	1078	15	8		51
	40	1152	1152	15	9		56
	50	1175	1175	18	9		61
	80	1200	1200	18	12		83
	100	1250	1250	18	12		96
12							
	10	942	942	15	8	5.2	44
	20	1006	1006	15	9		49
	30	1075	1075	15	10		54
	40	1142	1142	18	11		59
	50	1200	1200	18	12		64
	80	1280	1280	20	15		88
	100	1340	1340	20	15		98
	150	1400	1400	20	15		124
16							
	10	1769	1769	35	20	6.4	54
	20	2021	2021	35	22		59
	30	2274	2274	35	22		64
	40	2527	2527	40	25		69
	50	2780	2780	40	25		74
	80	2800	2800	50	27		89
	100	2850	2850	50	43		113
	150	2900	2900	50	43		138
20							
	10	2911	2911	60	30	7.55	56
	20	3143	3143	60	30		61
	30	3354	3354	60	30		66
	40	3612	3612	60	40		71
	50	3816	3816	70	50		76
	80	4032	4032	80	50		91
	100	4200	4200	85	80		121
	150	4400	4400	90	80		152
	200	4600	4600	90	80		177
25							
	10	3270	3270	100	60	8.55	64
	20	3744	3744	100	60		69
	30	4205	4205	100	60		74
	40	4643	4643	110	60		79
	50	4650	4650	120	60		84
	80	4700	4700	130	80		112
	100	4750	4750	130	80		129
	150	4800	4800	130	80		154
	200	4800	4800	130	80		179

Size 4 ... 10

Technical drawing of a rectangular plate with dimensions and features. The plate has a width of B13 and a height of H18. It features a central circular hole with a diameter of B6. There are four smaller circular holes, each with a diameter of B6, arranged in a 2x2 grid. The distance between the centers of these holes is B14. The plate has a thickness of H9. The drawing also shows a detail view of a corner with a radius of R5 and a detail view of a hole with a diameter of B6. The drawing is labeled with 'B6', 'B14', 'B13', 'H9', 'H18', 'H5', 'H6', 'H4', 'EE', '4', and '5'.



- | | | | |
|--|--|--|--|
| [1] Mounting thread (centring sleeves included in the scope of delivery) | [4] Supply port, advancing | L10 Distance between outer edge of yoke plate and housing | L18 Distance between centre of centring hole and outer edge of housing |
| [2] Through-holes for mounting the drive | [5] Supply port, retracting | | |
| | [6] Sensor slots for proximity switch SME/SMT-10 | L15 Distance between centre of centring hole and outer edge of slide | |
| [3] Centring holes (centring sleeves included in the scope of delivery) | [7] Centring hole | | |

Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	D1
4	28	27.4	18.35	9.4	5	3.55	6.3	11.95	27.5	2	17.2	12.4	23.15	16.15	M3
6	35	34.5	26.3	13.5	5	5	8.2	13.55	34.5	3.5	19.9	20	28.1	18.9	M3
8	42	41.3	31.45	16.6	10	6	10.3	16.25	41.5	4.57	24	24.1	33	24.4	M4
10	50	49	39.2	19.65	10	6.8	12.35	20.1	49	5	29.2	28	37.7	27	M4

Size	D2 ø	D3 ø	D4 ø	D5 ø	D6	D7 ø	EE	H1 ±0.08	H2	H3	H4	H5	H6	H7	H8
4	6.3	5 ^{H7}	3.3	6.2	M4x0.5	3 ^{H7}	M3	16	15.4	15.1	3.85	6.25	8.55	8.1	8.4
6	6.3	5 ^{H7}	3.3	6.2	M5x0.5	3 ^{H7}	M3	20	19	19.25	4.7	7.8	10.2	16.05	10.55
8	8.2	7 ^{H7}	4.3	8	M6x0.5	5 ^{H7}	M3	24	22.7	23	6.46	10.63	14.06	18.9	13.3
10	8.2	7 ^{H7}	4.3	8	M8x1	5 ^{H7}	M5	29	27.1	28	6.8	13.8	15.8	22.8	15.5

Size	H9	H10	H11	H12	H13	H14	H15	H16	H17	H18	H19	T3 +0.1	T4	T5	$\approx 2^1$	≈ 3
4	0.65	0.3	5	8	2.7	5.35	5.85	3.1	10.6	0.25	5.28	1.3	2.25	4	1.5	2
6	0.45	0.5	5	11.5	3.38	6.5	7.2	3.7	13.1	0.3	6.68	1.3	3.7	6	1.5	2.5
8	0.64	0.9	10	8.7	3.28	7.8	10.5	4.1	16.8	0.36	6.7	1.6	3.8	7.5	2	2.5
10	0.6	1.4	10	12.5	4.2	8.76	11.76	4.8	19.25	0.41	9	1.6	5.35	7.5	2.5	3

28

Datasheet

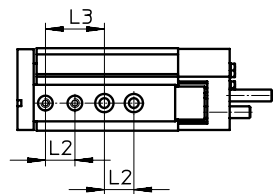
Stroke-dependent dimensions															
Size	Stroke	L1	L2	L5	L6	L7	L8	L9	L10	L11	L15 ±0.05	L16	L17	L18 ±0.05	L21
4	10	72.1	48	28.85	–	–	6.5	5.5	6.6	2.5	4	13.25	4.95	3	31
	20	81.2	57.1	37.95	10										36
	30	91.2	67.1	47.95	11										42
6	10	81.1	54	33.1	–	–	8	8	9.6	2.5	5.1	13.25	4.95	3.5	37
	20	91.1	64	43.1	14										42
	30	101.1	74	53.1											47
	40	111.1	84	63.1											52
	50	121.1	94	73.1											57
8	10	90.2	59.6	34.6	–	–	8	10	11.6	2.5	7	14.65	6.1	5.5	41
	20	100.2	69.6	44.6	10										46
	30	110.2	79.6	54.6	16										51
	40	120.2	89.6	64.6											56
	50	142.2	111.6	74.6											67
	80	172.2	141.6	104.6		16									82
10	10	103.1	66	41.3	–	–	11	10	11.6	2.5	6.4	18.5	7.5	5	43
	20	112.8	75.7	51											46
	30	122.8	85.7	61											51
	40	132.8	95.7	71											56
	50	142.8	105.7	81											61
	80	186.2	149.1	111	24										83
	100	206.2	169.1	131	24	24									96

Cushioning-dependent dimensions					
Size	Cushioning	L3 max.	L4 max.	≈ 1	
				For adjusting the cushioning stroke	For adjusting the end position
4	P	15.2	7.8	–	1.5
	E	5.7	0	–	1.5
	P1	14	6	1.3	2.5
6	P	17.6	8.1	–	1.5
	E	6.6	0	–	1.5
	P1	15.5	5.8	1.5	3
8	P	21.1	10.7	–	2
	E	6.6	0	–	2
	P1	19	9.1	2	4
	Y3	24.3	23.9	–	2
10	P	22.8	12.5	–	2.5
	E	8.8	0	–	2.5
	P1	20.5	10.2	2.5	5
	Y3	25.5	14.9	–	2.5
	Y11	30.4	19.9	–	2

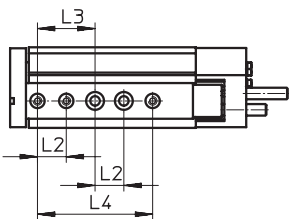
Datasheet

Hole pattern for mounting threads and centring holes

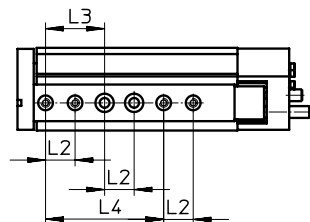
DGSL-4-10



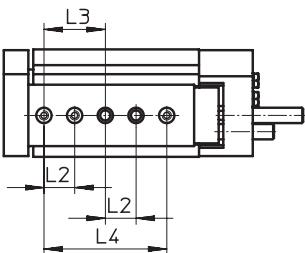
DGSL-4-20



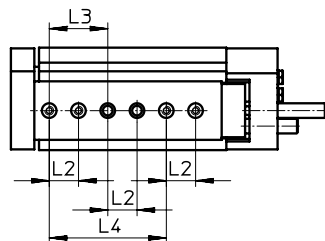
DGSL-4-30



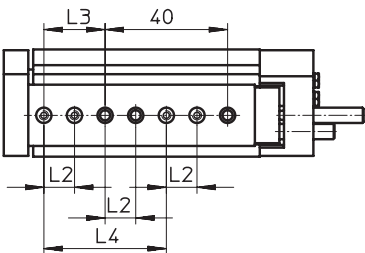
DGSL-6-10



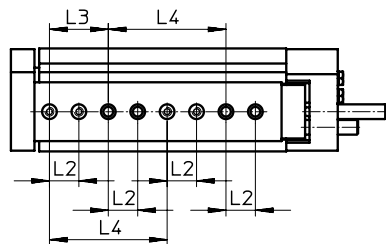
DGSL-6-20



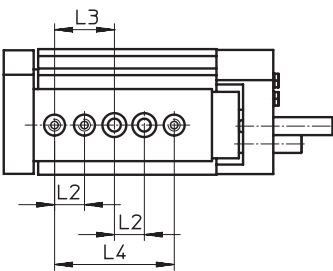
DGSL-6-30



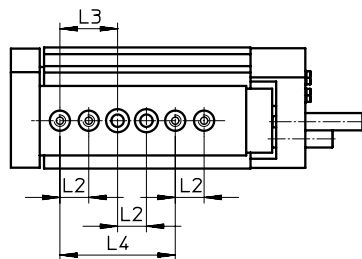
DGSL-6-40/50



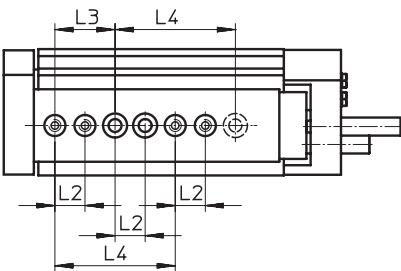
DGSL-8-10



DGSL-8-20



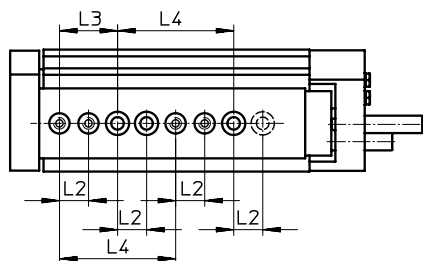
DGSL-8-30



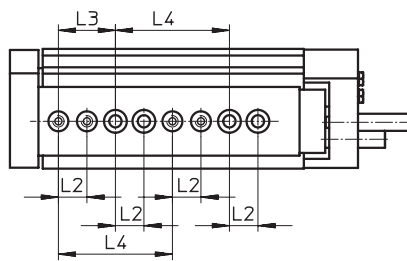
Datasheet

Hole pattern for mounting threads and centring holes

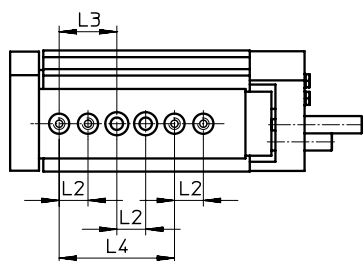
DGSL-8-40



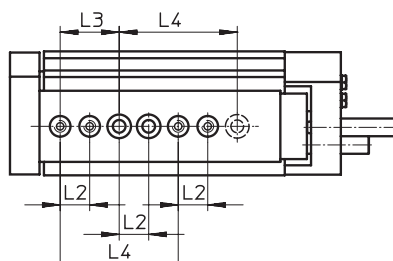
DGSL-8-50/80



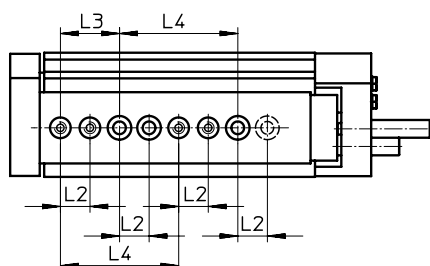
DGSL-10-10



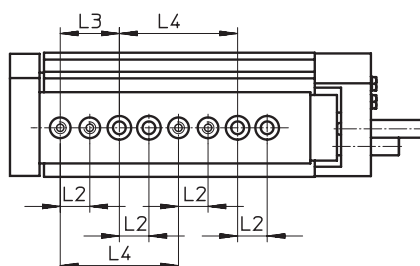
DGSL-10-20



DGSL-10-30

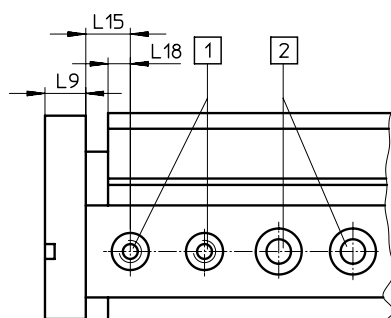


DGSL-10-40 ... 100



Distances from the yoke plate to the mounting threads and centring holes

DGSL-4 ... 10



- [1] Centring holes with thread
[2] Through-holes for mounting the drive

Size	L2 ¹⁾	L3 ¹⁾	L4 ¹⁾	L9	L15 ±0.05	L18
4	10	20	40	5.5	4	3
6	10	20	40	8	5.1	3.5
8	10	20	40	10	7	5.5
10	10	20	40	10	6.4	5

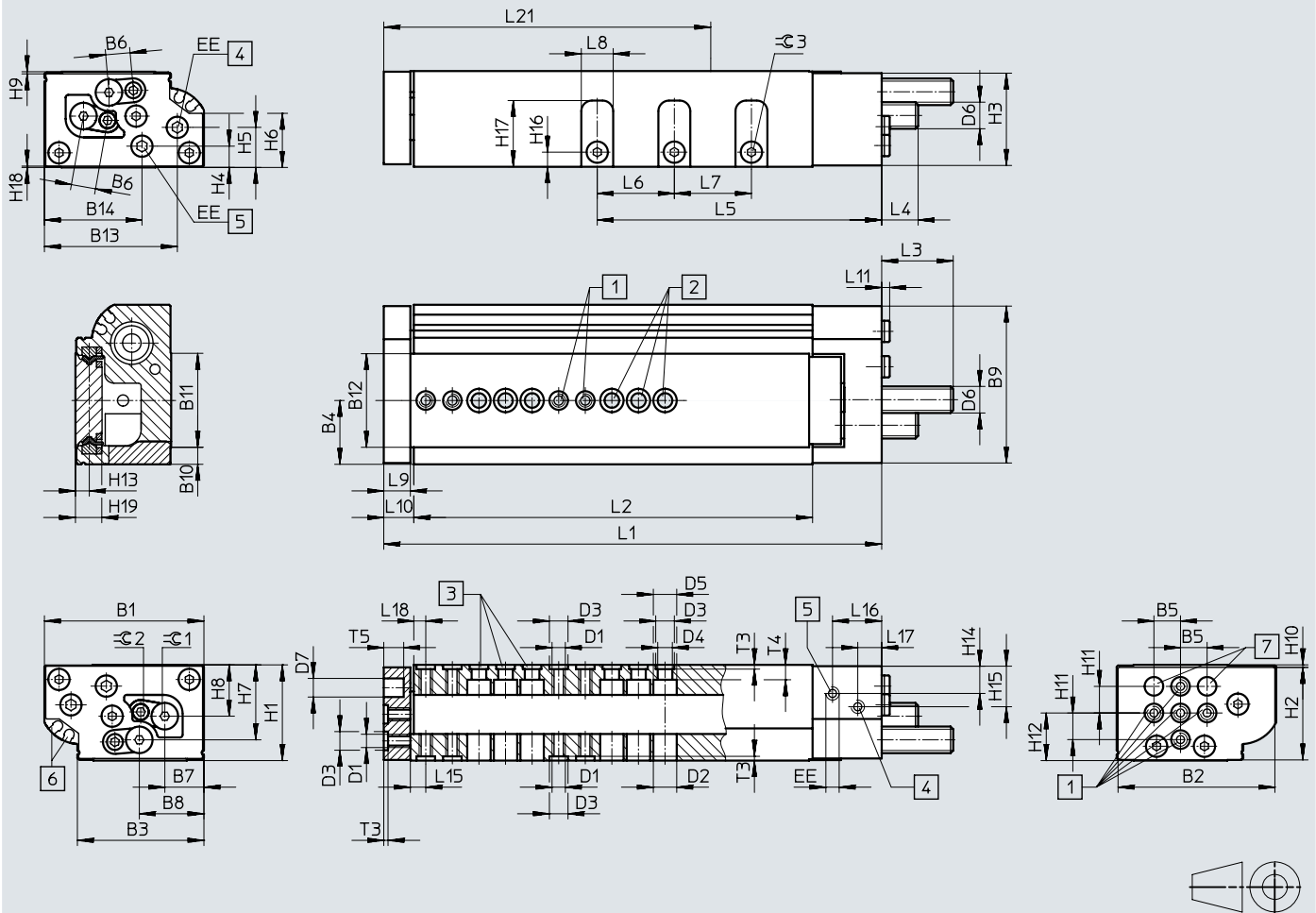
1) Tolerance for centring hole ±0.02
Tolerance for through-hole ±0.1

Datasheet

Dimensions

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Size 12/16



- [1] Mounting thread (centring sleeves included in the scope of delivery)
 [2] Through-holes for mounting the drive
 [3] Centring holes (centring sleeves included in the scope of delivery)
 [4] Supply port, advancing
 [5] Supply port, retracting
 [6] Sensor slots for proximity switch SME/SMT-10
 [7] Centring hole
- L10 Distance between outer edge of yoke plate and housing
 L15 Distance between centre of centring hole and outer edge of slide
 L18 Distance between centre of centring hole and outer edge of housing

General dimensions

Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	D1
12	60	59	47.6	24	10	9.2	14.7	24.3	59	6.45	35.25	35.2	50	36.7	M5
16	66	65	53.5	26.7	10	11.1	16.7	27.5	65	7.75	37.9	38	50.4	36.7	M5

Size	D2 ∅	D3 ∅	D4 ∅	D5 ∅	D6	D7 ∅	EE	H1 ±0.08	H2	H3	H4	H5	H6	H7	H8
12	9	7 ^{H7}	5.5	9	M10x1	8 ^{H7}	M5	36	34.8	34.7	8	15.1	20.35	28.2	19.3
16	9	7 ^{H7}	5.5	9	M12x1	8 ^{H7}	M5	40	38	39	8.5	16.7	20.6	31.7	20.8

Size	H9	H10	H11	H12	H13	H14	H15	H16	H17	H18	H19	T3 +0.1	T4	T5	∠2	∠3
12	0.8	0.95	10	17.9	5.2	10.75	15.75	5.5	24.9	0.5	10.1	1.6	5.6	7.5	3	3
16	0.5	1.5	10	20	6.4	10.5	16.7	7	26.6	0.5	12.5	1.6	6.1	9	4	4

Datasheet

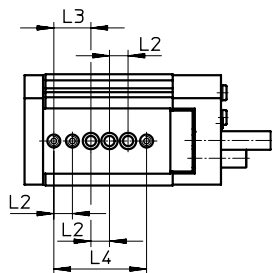
Stroke-dependent dimensions															
Size	Stroke	L1	L2	L5	L6	L7	L8	L9	L10	L11	L15 ±0.05	L16	L17	L18 ±0.05	L21
12	10	106.2	68.6	42.4	–	–	12	10	11.6	2.5	5.8	18.5	9	4.5	44
	20	116.2	78.6	52.4											49
	30	126.2	88.6	62.4											54
	40	136.2	98.6	72.4											59
	50	146.2	108.6	82.4											64
	80	197.6	160	112.4	29										88
	100	217.6	180	132.4											98
	150	267.6	230	182.4		29									124
16	10	124.1	82.5	45	–	–	14	12	13.6	2.5	6.8	21	10	5.5	54
	20	134.6	93	54.6											59
	30	144.6	103	64.6											64
	40	154.6	113	74.6											69
	50	164.6	123	84.6											74
	80	194.6	153	114.6	35										89
	100	243.6	202	134.6											113
	150	293.6	252	184.6											138

Cushioning-dependent dimensions					
Size	Cushioning	L3 max.	L4 max.	≈ 1	
				For adjusting the cushioning stroke	For adjusting the end position
12	P	28.1	14.9	–	3
	E	8.8	0	–	3
	P1	26	12.8	3	6
	Y3	36.9	23.7	–	3
	Y11	42.2	18.7	–	2.5
16	P	42.3	26.1	–	4
	E	8.8	0	–	4
	P1	40	23.8	4	8
	Y3	51.9	35.7	–	4
	Y11	55.4	38.9	–	3

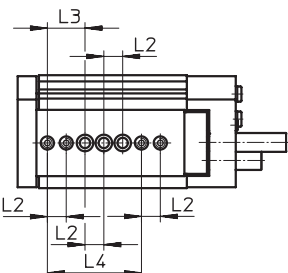
Datasheet

Hole pattern for mounting threads and centring holes

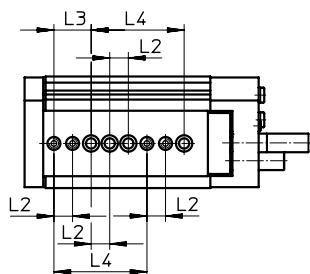
DGSL-12-10



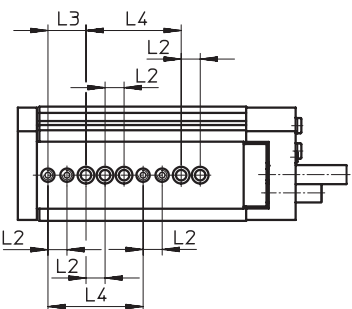
DGSL-12-20



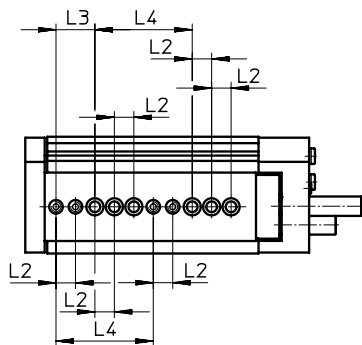
DGSL-12-30



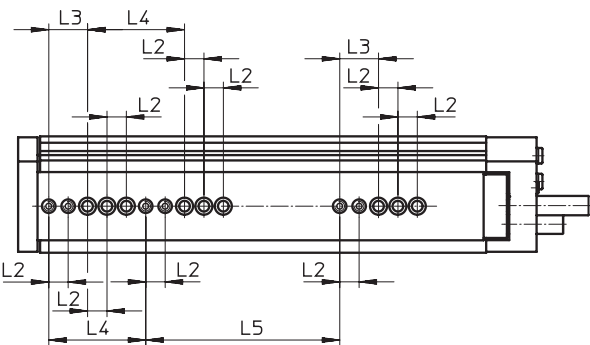
DGSL-12-40



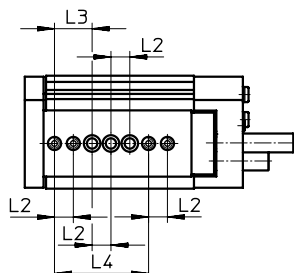
DGSL-12-50 ... 100



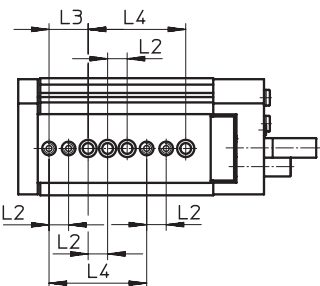
DGSL-12-150



DGSL-16-10



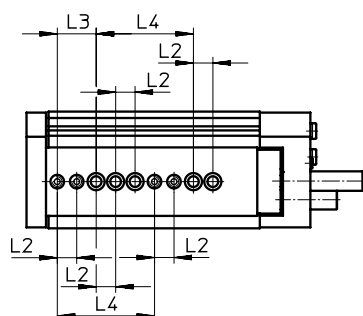
DGSL-16-20



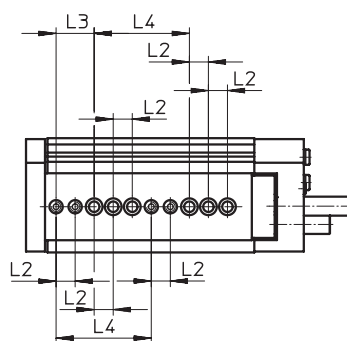
Datasheet

Hole pattern for mounting threads and centring holes

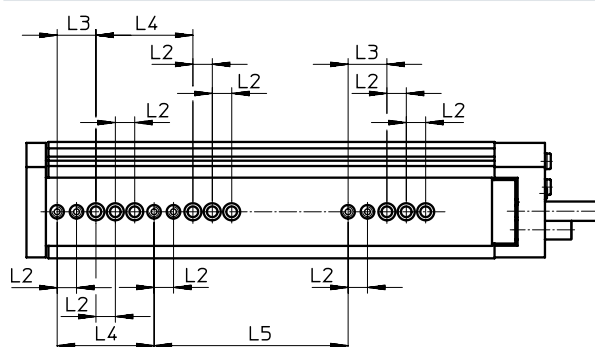
DGSL-16-30



DGSL-16-40 ... 100

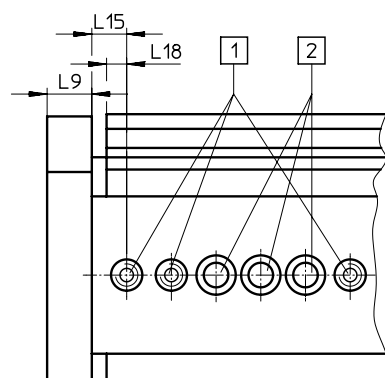


DGSL-16-150



Distances from the yoke plate to the mounting threads and centring holes

DGSL-12/16



- [1] Centring holes with thread
[2] Through-holes for mounting the drive

Size	L2 ¹⁾	L3 ¹⁾	L4 ¹⁾	L5 ±0.03	L9	L15 ±0.05	L18 ±0.05
12	10	20	50	100	10	5.8	4.5
16	10	20	50	100	12	6.8	5.5

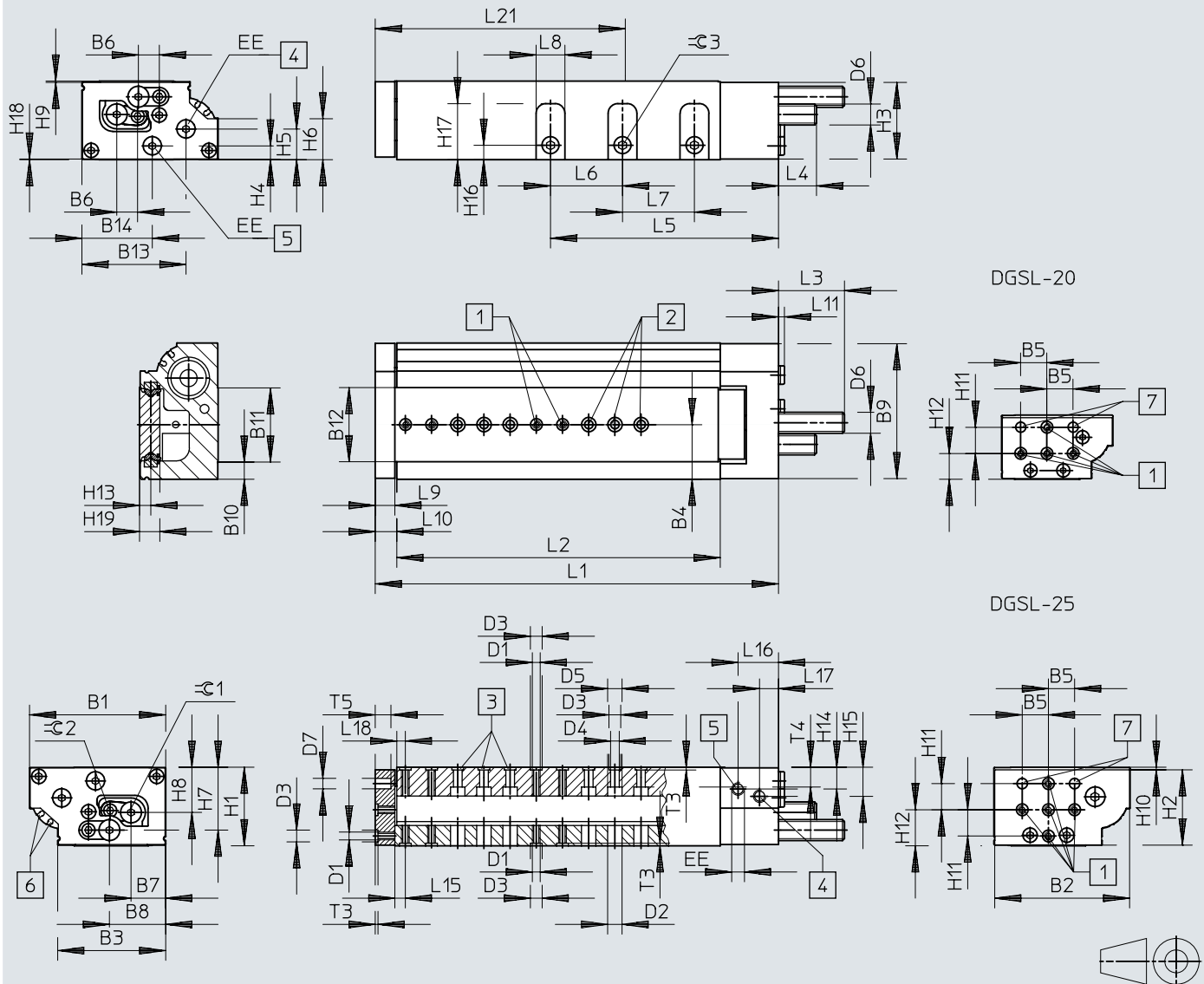
1) Tolerance for centring hole ±0.02
Tolerance for through-hole ±0.1

Datasheet

Dimensions

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Size 20/25



- | | | | |
|--|--|--|--|
| [1] Mounting thread (centring sleeves included in the scope of delivery) | [4] Supply port, advancing | L10 Distance between outer edge of yoke plate and housing | L18 Distance between centre of centring hole and outer edge of housing |
| [2] Through-holes for mounting the drive | [5] Supply port, retracting | L15 Distance between centre of centring hole and outer edge of slide | |
| [3] Centring holes (centring sleeves included in the scope of delivery) | [6] Sensor slots for proximity switch SME/SMT-10 | | |
| | [7] Centring hole | | |

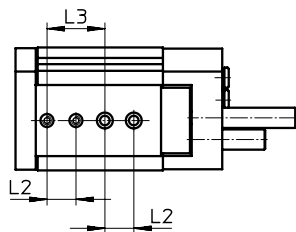
Datasheet

General dimensions																							
Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	D1								
20	85	84	68.85	34.5	20	14.15	21.4	36.35	83.4	10	48.9	49.2	64.1	48.6	M6								
25	104	103	82.6	41.6	20	16.2	26.4	43.05	103	13.25	56.5	56.7	79.3	53.65	M6								
Size	D2 Ø	D3 Ø	D4 Ø	D5 Ø	D6	D7 Ø	EE	H1 ±0.08	H2	H3	H4	H5	H6	H7	H8								
20	11.2	9 ^{H7}	6.6	11	M14x1	8 ^{H7}	G1/8	49	46.5	47.7	10.3	20.6	23.2	38.2	26.1								
25	11.2	9 ^{H7}	6.6	11	M16x1	8 ^{H7}	G1/8	60	57.5	58.5	10.45	23.35	31.15	47.95	34.5								
Size	H9	H10	H11	H12	H13	H14	H15	H16	H17	H18	H19	T3 +0.1	T4	T5	≈ 2	≈ 3							
20	0.5	2	20	19.6	7.55	14.7	14.7	10	33.3	0.8	14.6	2.1	8.6	10	4	5							
25	1	2	20	27.5	8.55	16.55	21.15	11	42.7	0.45	15.6	2.1	15	12	5	6							
Stroke-dependent dimensions																							
Size	Stroke	L1	L2	L5	L6	L7	L8	L9	L10	L11	L15 ±0.05	L16	L17	L18 ±0.05	L21								
20	10	141.2	84.6	59.1	–	–	17	14	15.6	4.6	7.8	30.5	12	6.5	56								
	20	151.2	94.6	69.1											61								
	30	161.2	104.6	79.1											66								
	40	171.2	114.6	89.1											71								
	50	183.2	126.6	99.1											76								
	80	211.2	154.6	129.1											91								
	100	270.2	213.6	149.1	44										121								
	150	333.2	276.6	199.1											152								
	200	383.2	326.6	249.1											44	177							
25	10	157.1	96	63.7	–	–	22	15	16.6	4.6	8	32.3	14.5	6.5	64								
	20	167.1	106	72.2											69								
	30	177.1	116	82.2											74								
	40	187.1	126	92.2											79								
	50	197.1	136	102.2											84								
	80	253.1	192	132.2	55										112								
	100	286.1	225	152.2											129								
	150	338.1	277	202.2											154								
	200	388.1	327	252.2											179								
Cushioning-dependent dimensions																							
Size	Cushioning	L3 max.	L4 max.	≈ 1																			
				For adjusting the cushioning stroke	For adjusting the end position																		
20	P	52.4	31.2	–	4																		
	E	8.8	0	–	4																		
	P1	50.1	28.9	4	8																		
	Y3	55.5	34.3	–	4																		
	Y11	67.4	45.9	–	4																		
25	P	51.9	30.5	–	5																		
	E	8.8	0	–	5																		
	P1	49.6	28.2	5	10																		
	Y3	65.2	43.8	–	5																		
	Y11	78.4	56.9	–	4																		

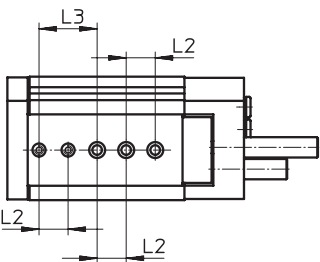
Datasheet

Hole pattern for mounting threads and centring holes

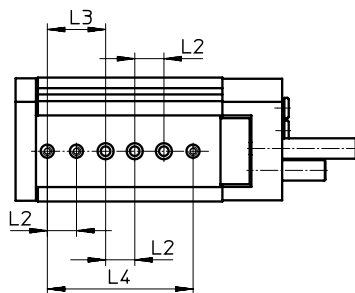
DGSL-20-10/20



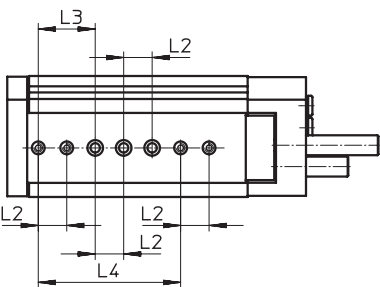
DGSL-20-30/40



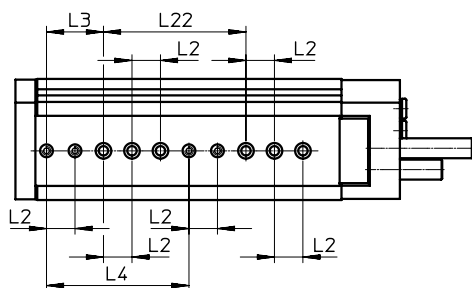
DGSL-20-50



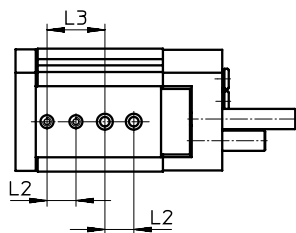
DGSL-20-80



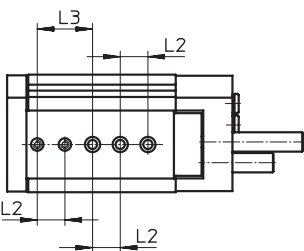
DGSL-20-100 ... 200



DGSL-25-10



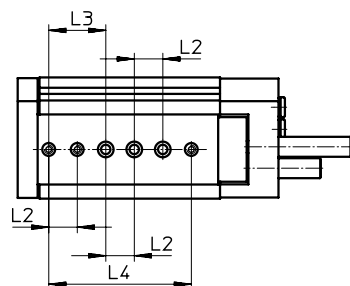
DGSL-25-20



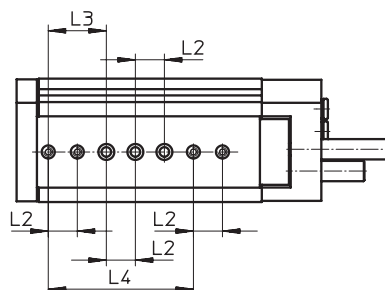
Datasheet

Hole pattern for mounting threads and centring holes

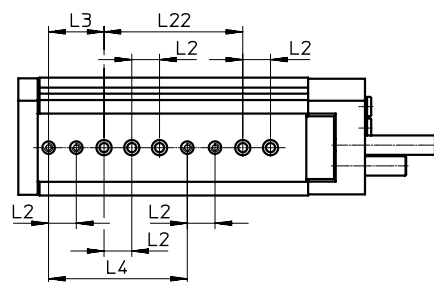
DGSL-25-30/40



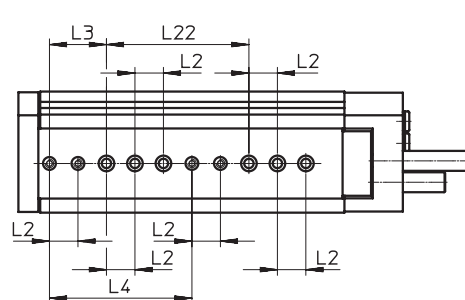
DGSL-25-50



DGSL-25-80

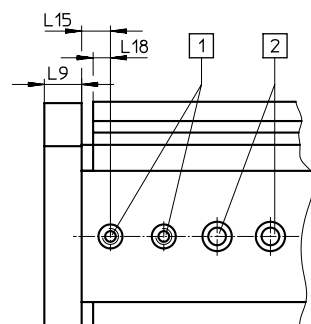


DGSL-25-100 ... 200



Distances from the yoke plate to the mounting threads and centring holes

DGSL-20/25



- [1] Centring holes with thread
[2] Through-holes for mounting the drive

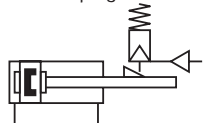
Size	L2 ¹⁾	L3 ¹⁾	L4	L9	L15 ±0.05	L18 ±0.05	L22
20	20	40	100 ¹⁾	14	7.8	6.5	100±0.03
25	20	40	100±0.03	15	8	6.5	100 ¹⁾

- 1) Tolerance for centring hole ±0.02
Tolerance for through-hole ±0.1

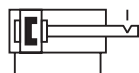
Datasheet

Function

C – Clamping unit

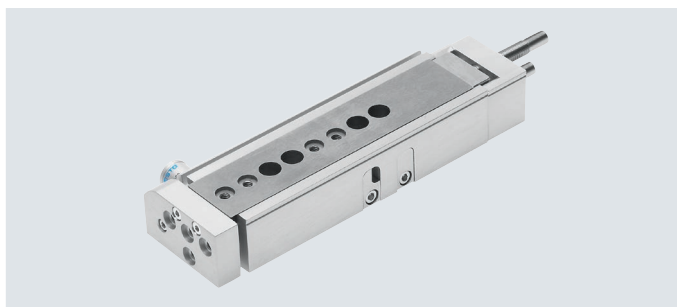


E3 – End-position locking



Size
6 ... 25

Sets of wearing parts
→ Page 45



 Note

Additional measures are required for use in safety-related applications; in Europe, for example, the standards listed under the EC Machinery Directive must be observed. Without additional measures in accordance with legally specified minimum requirements, the product is not suitable as a safety-related component in control systems.

General technical data – Clamping unit

Size	6	8	10	12	16	20	25
Function	• Mechanical clamping • For fixing the slide in any position • Frictional locking						
Clamping type with operating direction	At both ends						
	Clamping via spring force, release via compressed air						
Pneumatic connection	M5						
Mounting position	Any						
Static holding force [N]	80	80	180	180	350	350	600
Product weight [g]	10	10	15	15	50	50	50

Operating and environmental conditions – Clamping unit

Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]	
Note on the operating/pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)	
Min. release pressure		
	[MPa]	0.3
	[bar]	3
Max. operating pressure		
	[MPa]	≤ 1
	[bar]	≤ 10

General technical data – End-position locking

Size	6	8	10	12	16	20	25
Function	• Mechanical locking when the end position is reached • For fixing the slide in the unpressurised, retracted state • Form-fitting						
Clamping type with operating direction	At both ends						
	Clamping via spring force, unlock via compressed air						
Pneumatic connection	M5						
Mounting position	Any						
Static holding force [N]	60	60	160	160	250	380	640
Product weight [g]	13	13	26	26	64	64	65

Operating and environmental conditions – End-position locking

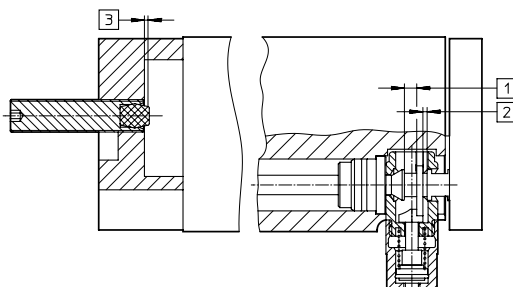
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]	
Note on the operating/pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)	
Operating pressure		
	[MPa]	0.3 ... 0.8
	[bar]	3 ... 8

Datasheet

Adjustable end-position range

When using end-position locking (E3), the adjustable end-position range, the retracted end position, is reduced by the following values.

- [1] Axial adjustment range
- [2] Max. cushioning stroke
- [3] Adjustable end-position range

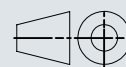
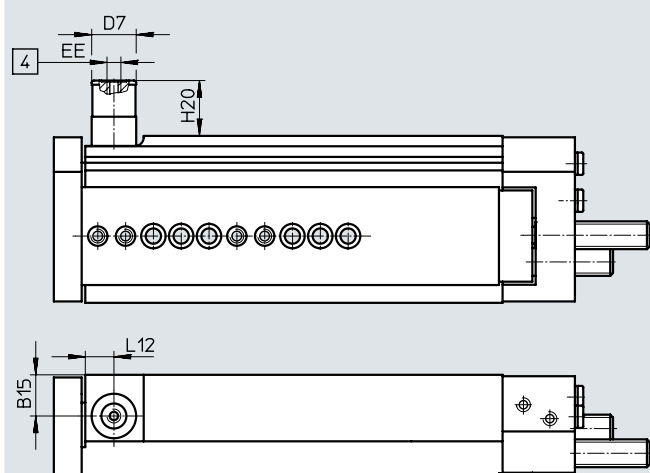


Size	[3]
6, 8	Max. 1.5 mm
10, 12	Max. 2.3 mm
16, 20, 25	Max. 2.7 mm

Dimensions

Download CAD data → www.festo.com

C – Clamping unit / E3 – End-position locking



[4] Compressed air supply port

Size	B15	D7 Ø	EE	H20		L12
				C	E3	
6	7.2	12	M5	10.7	21.2	7.3
8	9.9	12		10.5	21	7.3
10	11.2	16		11.8	21.2	10.5
12	14.8	16		10.5	19.9	10.3
16	14	20		27.5	30.5	13
20	17	20		21.3	24.3	14
25	22.55	20		17.75	20.65	14

Datasheet

Ordering data							
Size	Stroke [mm]	Part no.	Type	Size	Stroke [mm]	Part no.	Type
With cushioning P				With cushioning Y3			
4	10	543910	DGSL-4-10-PA	4	10	–	
	20	543911	DGSL-4-20-PA		20		
	30	543912	DGSL-4-30-PA		30		
6	10	543916	DGSL-6-10-PA	6	10	–	
	20	543917	DGSL-6-20-PA		20		
	30	543918	DGSL-6-30-PA		30		
	40	543919	DGSL-6-40-PA		40		
	50	543920	DGSL-6-50-PA		50		
8	10	543926	DGSL-8-10-PA	8	10	–	
	20	543927	DGSL-8-20-PA		20		
	30	543928	DGSL-8-30-PA		30	543938	DGSL-8-30-Y3A
	40	543929	DGSL-8-40-PA		40	543939	DGSL-8-40-Y3A
	50	543930	DGSL-8-50-PA		50	543940	DGSL-8-50-Y3A
	80	543931	DGSL-8-80-PA		80	543941	DGSL-8-80-Y3A
10	10	543942	DGSL-10-10-PA	10	10	–	
	20	543943	DGSL-10-20-PA		20		
	30	543944	DGSL-10-30-PA		30	543956	DGSL-10-30-Y3A
	40	543945	DGSL-10-40-PA		40	543957	DGSL-10-40-Y3A
	50	543946	DGSL-10-50-PA		50	543958	DGSL-10-50-Y3A
	80	543947	DGSL-10-80-PA		80	543959	DGSL-10-80-Y3A
	100	543948	DGSL-10-100-PA		100	543960	DGSL-10-100-Y3A
12	10	543961	DGSL-12-10-PA	12	10	–	
	20	543962	DGSL-12-20-PA		20		
	30	543963	DGSL-12-30-PA		30	543977	DGSL-12-30-Y3A
	40	543964	DGSL-12-40-PA		40	543978	DGSL-12-40-Y3A
	50	543965	DGSL-12-50-PA		50	543979	DGSL-12-50-Y3A
	80	543966	DGSL-12-80-PA		80	543980	DGSL-12-80-Y3A
	100	543967	DGSL-12-100-PA		100	543981	DGSL-12-100-Y3A
16	10	543983	DGSL-16-10-PA		150	543982	DGSL-12-150-Y3A
	20	543984	DGSL-16-20-PA	16	10	–	
	30	543985	DGSL-16-30-PA		20		
	40	543986	DGSL-16-40-PA		30	543999	DGSL-16-30-Y3A
	50	543987	DGSL-16-50-PA		40	544000	DGSL-16-40-Y3A
	80	543988	DGSL-16-80-PA		50	544001	DGSL-16-50-Y3A
	100	543989	DGSL-16-100-PA		80	544002	DGSL-16-80-Y3A
	150	543990	DGSL-16-150-PA		100	544003	DGSL-16-100-Y3A
					150	544004	DGSL-16-150-Y3A

Datasheet

Ordering data							
Size	Stroke [mm]	Part no.	Type	Size	Stroke [mm]	Part no.	Type
With cushioning P				With cushioning Y3			
20	10	544005	DGSL-20-10-PA	20	10	—	
	20	544006	DGSL-20-20-PA		20		
	30	544007	DGSL-20-30-PA		30	544023	DGSL-20-30-Y3A
	40	544008	DGSL-20-40-PA		40	544024	DGSL-20-40-Y3A
	50	544009	DGSL-20-50-PA		50	544025	DGSL-20-50-Y3A
	80	544010	DGSL-20-80-PA		80	544026	DGSL-20-80-Y3A
	100	544011	DGSL-20-100-PA		100	544027	DGSL-20-100-Y3A
	150	544012	DGSL-20-150-PA		150	544028	DGSL-20-150-Y3A
	200	544013	DGSL-20-200-PA		200	544029	DGSL-20-200-Y3A
25	10	544030	DGSL-25-10-PA	25	10	—	
	20	544031	DGSL-25-20-PA		20		
	30	544032	DGSL-25-30-PA		30	544048	DGSL-25-30-Y3A
	40	544033	DGSL-25-40-PA		40	544049	DGSL-25-40-Y3A
	50	544034	DGSL-25-50-PA		50	544050	DGSL-25-50-Y3A
	80	544035	DGSL-25-80-PA		80	544051	DGSL-25-80-Y3A
	100	544036	DGSL-25-100-PA		100	544052	DGSL-25-100-Y3A
	150	544037	DGSL-25-150-PA		150	544053	DGSL-25-150-Y3A
	200	544038	DGSL-25-200-PA		200	544054	DGSL-25-200-Y3A

Datasheet

Ordering data							
Size	Stroke [mm]	Part no.	Type	Size	Stroke [mm]	Part no.	Type
With cushioning P1				With cushioning E			
4	10	543913	DGSL-4-10-P1A	4	10	570158	DGSL-4-10-EA
	20	543914	DGSL-4-20-P1A		20	570159	DGSL-4-20-EA
	30	543915	DGSL-4-30-P1A		30	570160	DGSL-4-30-EA
6	10	543921	DGSL-6-10-P1A	6	10	570161	DGSL-6-10-EA
	20	543922	DGSL-6-20-P1A		20	570162	DGSL-6-20-EA
	30	543923	DGSL-6-30-P1A		30	570163	DGSL-6-30-EA
	40	543924	DGSL-6-40-P1A		40	570164	DGSL-6-40-EA
	50	543925	DGSL-6-50-P1A		50	570165	DGSL-6-50-EA
8	10	543932	DGSL-8-10-P1A	8	10	570166	DGSL-8-10-EA
	20	543933	DGSL-8-20-P1A		20	570167	DGSL-8-20-EA
	30	543934	DGSL-8-30-P1A		30	570168	DGSL-8-30-EA
	40	543935	DGSL-8-40-P1A		40	570169	DGSL-8-40-EA
	50	543936	DGSL-8-50-P1A		50	570170	DGSL-8-50-EA
	80	543937	DGSL-8-80-P1A		80	570171	DGSL-8-80-EA
10	10	543949	DGSL-10-10-P1A	10	10	570172	DGSL-10-10-EA
	20	543950	DGSL-10-20-P1A		20	570173	DGSL-10-20-EA
	30	543951	DGSL-10-30-P1A		30	570174	DGSL-10-30-EA
	40	543952	DGSL-10-40-P1A		40	570175	DGSL-10-40-EA
	50	543953	DGSL-10-50-P1A		50	570176	DGSL-10-50-EA
	80	543954	DGSL-10-80-P1A		80	570177	DGSL-10-80-EA
	100	543955	DGSL-10-100-P1A		100	570178	DGSL-10-100-EA
12	10	543969	DGSL-12-10-P1A	12	10	570179	DGSL-12-10-EA
	20	543970	DGSL-12-20-P1A		20	570180	DGSL-12-20-EA
	30	543971	DGSL-12-30-P1A		30	570181	DGSL-12-30-EA
	40	543972	DGSL-12-40-P1A		40	570182	DGSL-12-40-EA
	50	543973	DGSL-12-50-P1A		50	570183	DGSL-12-50-EA
	80	543974	DGSL-12-80-P1A		80	570184	DGSL-12-80-EA
	100	543975	DGSL-12-100-P1A		100	570185	DGSL-12-100-EA
	150	543976	DGSL-12-150-P1A		150	570186	DGSL-12-150-EA

Datasheet

Ordering data							
Size	Stroke [mm]	Part no.	Type	Size	Stroke [mm]	Part no.	Type
16	10	543991	DGSL-16-10-P1A	16	10	570187	DGSL-16-10-EA
	20	543992	DGSL-16-20-P1A		20	570188	DGSL-16-20-EA
	30	543993	DGSL-16-30-P1A		30	570189	DGSL-16-30-EA
	40	543994	DGSL-16-40-P1A		40	570190	DGSL-16-40-EA
	50	543995	DGSL-16-50-P1A		50	570191	DGSL-16-50-EA
	80	543996	DGSL-16-80-P1A		80	570192	DGSL-16-80-EA
	100	543997	DGSL-16-100-P1A		100	570193	DGSL-16-100-EA
	150	543998	DGSL-16-150-P1A		150	570194	DGSL-16-150-EA
20	10	544014	DGSL-20-10-P1A	20	10	570195	DGSL-20-10-EA
	20	544015	DGSL-20-20-P1A		20	570196	DGSL-20-20-EA
	30	544016	DGSL-20-30-P1A		30	570197	DGSL-20-30-EA
	40	544017	DGSL-20-40-P1A		40	570198	DGSL-20-40-EA
	50	544018	DGSL-20-50-P1A		50	570199	DGSL-20-50-EA
	80	544019	DGSL-20-80-P1A		80	570200	DGSL-20-80-EA
	100	544020	DGSL-20-100-P1A		100	570201	DGSL-20-100-EA
	150	544021	DGSL-20-150-P1A		150	570202	DGSL-20-150-EA
25	10	544039	DGSL-25-10-P1A	25	10	570204	DGSL-25-10-EA
	20	544040	DGSL-25-20-P1A		20	570205	DGSL-25-20-EA
	30	544041	DGSL-25-30-P1A		30	570206	DGSL-25-30-EA
	40	544042	DGSL-25-40-P1A		40	570207	DGSL-25-40-EA
	50	544043	DGSL-25-50-P1A		50	570208	DGSL-25-50-EA
	80	544044	DGSL-25-80-P1A		80	570209	DGSL-25-80-EA
	100	544045	DGSL-25-100-P1A		100	570210	DGSL-25-100-EA
	150	544046	DGSL-25-150-P1A		150	570211	DGSL-25-150-EA
	200	544047	DGSL-25-200-P1A		200	570212	DGSL-25-200-EA

Ordering data for modular products → Page 46

Ordering data – Sets of wearing parts					
Size	Part no.	Type	Size	Part no.	Type
4	713743	DGSL-4-...	12	713747	DGSL-12-...
6	713744	DGSL-6-...	16	713748	DGSL-16-...
8	713745	DGSL-8-...	20	713749	DGSL-20-...
10	713746	DGSL-10-...	25	713750	DGSL-25-...

Ordering data – Modular product system

Ordering table											
Size	4	6	8	10	12	16	20	25	Conditions	Code	Enter code
Module no.	543902	543903	543904	543905	543906	543907	543908	543909			
Function	Mini slide with recirculating ball bearing guide									DGSL	DGSL
Size	4	6	8	10	12	16	20	25		-...	
Stroke [mm]	10									-10	
	20									-20	
	30									-30	
	—	40								-40	
	—	50								-50	
	—	—	80							-80	
	—	—	—	100						-100	
	—	—	—	—	150					-150	
	—	—	—	—	—	—	200			-200	
Clamping unit	—	Attached								-C	
End-position locking	—	With retracted piston rod							[1]	-E3	
Cushioning	Elastic cushioning rings/pads at both ends, end positions adjustable									-P	
	Elastic cushioning rings/pads at both ends, end positions adjustable, with fixed stop									-P1	
	—		Progressive shock absorber, at both ends						[2]	-Y3	
	Elastic cushioning rings/pads at both ends, end positions adjustable, short design									-E	
	—			Progressive shock absorber with reducing sleeve, at both ends					[2]	-Y11	
	No cushioning								[2]	-N	
Position sensing	Via proximity switch									A	A

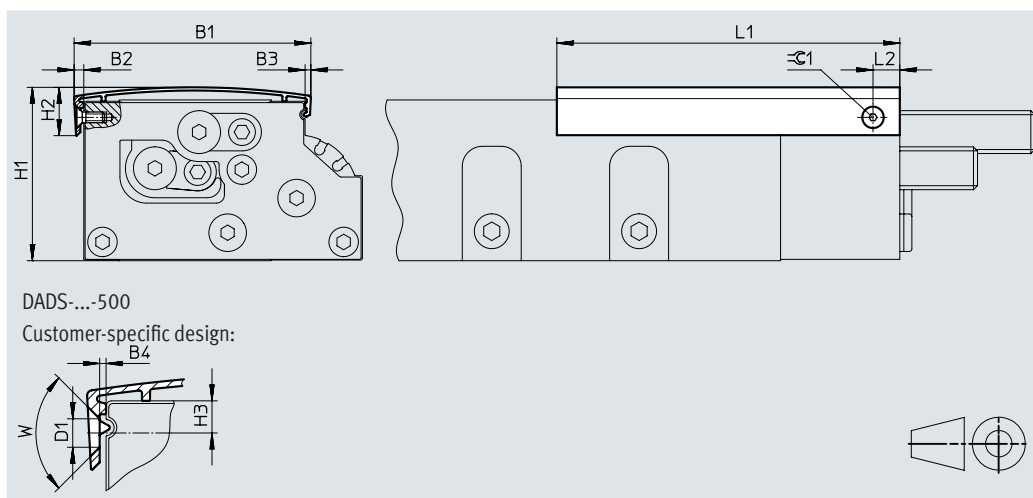
[1] E3 Not with clamping unit C

[2] Y3, Y11 Minimum stroke 30 mm

Accessories

Covering DADS

Material:
Anodised aluminium
RoHS-compliant



DADS-...-500

Customer-specific design:

Dimensions and ordering data																	
For size	Length [mm]	B1	B2	B3	B4	D1	H1	H2	H3	L1	L2	W	⌀G1	Weight [g]	Part no.	Type	
4	30	22	1.9	–	0.4	2.8	17.9	7.5	2	40	4.5	90°	–	2	1086663	DADS-AB-G6-4-30	
	500									500				27	1212468	DADS-AB-G6-4-500	
6	50	31.2	1.4	–	0	2.8	22	8.2	2.5	63	6	90°	–	4	1066625	DADS-AB-G6-6-50	
	500									500				33	1212476	DADS-AB-G6-6-500	
8	80	36.3	1.9	–	0.3	2.8	26.5	8.2	2	93	7	90°	–	8	1087413	DADS-AB-G6-8-80	
	500									500				42	1212478	DADS-AB-G6-8-500	
10	50	43.6	2.8	2.2	1.2	3.4	32	12	3.4	70	10	90°	2	11	1162400	DADS-AB-G6-10-50	
	100									120				18	1090689	DADS-AB-G6-10-100	
	500									500				75	1212479	DADS-AB-G6-10-500	
12	50	51.7	2.7	2	0.5	3.4	38.8	12.8	4.25	72	10	90°	2	12	1162406	DADS-AB-G6-12-50	
	150									170				28	1090732	DADS-AB-G6-12-150	
	500									500				82	1212480	DADS-AB-G6-12-500	
16	50	60	4.3	3.1	2.25	3.4	43.7	15.2	5	73	10	90°	2	21	1162410	DADS-AB-G6-16-50	
	150									173				49	1066591	DADS-AB-G6-16-150	
	500									500				141	1212503	DADS-AB-G6-16-500	
20	50	74.8	3.6	2.8	1.2	4.4	53.2	18.9	6.5	74	10	90°	2.5	28	1162412	DADS-AB-G6-20-50	
	100									124				46	1162415	DADS-AB-G6-20-100	
	200									224				83	1090823	DADS-AB-G6-20-200	
	500									500				184	1212521	DADS-AB-G6-20-500	
25	50	88.4	3.5	2.7	0.7	4.4	64.7	18.3	6	78	10	90°	2.5	34	1162417	DADS-AB-G6-25-50	
	100									128				55	1162419	DADS-AB-G6-25-100	
	200									228				98	1090895	DADS-AB-G6-25-200	
	500									500				213	1212523	DADS-AB-G6-25-500	



Note

With the 500 mm covers, the mounting hole must be made by the customer.

The cover can be shortened as required by the customer.

Accessories

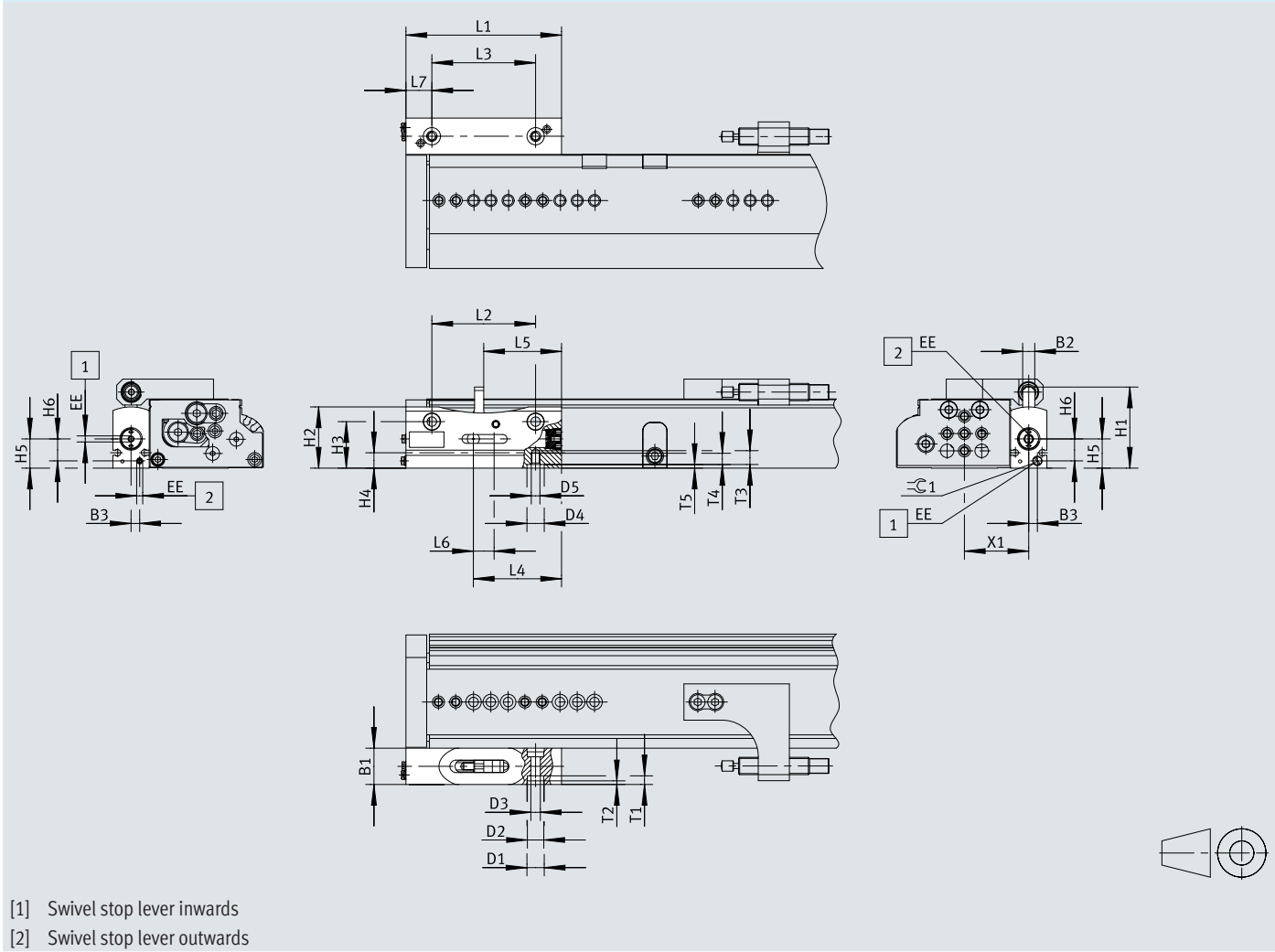
Intermediate-position module DADM

- The intermediate-position module enables an additional adjustable position within the stroke range. The module is attached separately, directly next to the mini slide. It can be mounted anywhere along the mini slide.
- The associated shock absorber retainer → page 50 can be attached at several points on the slide. The position can be precisely set with the help of the shock absorber.
- The stop lever positions can be sensed using proximity switches SME/SMT
→ Page 52
- Push-in fittings are not included in the scope of delivery

Material:
Housing:
Wrought aluminium alloy
Lever:
High-alloy stainless steel
RoHS-compliant

Dimensions and ordering data

Datasheets → Internet: dadm



 **Note**
With DADM-EP-G6-10: SME/SMT-10
With DADM-EP-G6-16: SME/SMT-8

For size	B1	B2	B3	D1 Ø H7	D2 Ø	D3 Ø	D4 Ø H7	D5	EE	H1	H2
			±0.1								
12, 16	21	7	5	10	9.5	5.5	10	M5	M3	46.9	35.4
20, 25	26.5	9	5.5	12	11	6.6	12	M6	M5	65.2	47.4

Accessories

For size	H3	H4	H5	H6	L1	L2	L3	L4	L5	L6	L7
	±0.1		±0.1	±0.1		±0.1	±0.1				±0.1
12, 16	26.9	8.9	16.9	12.7	90	60	60	51	45	12	15
20, 25	36.4	12.4	23.4	17	120	80	80	68	60	16	20

For size	T1	T2	T3	T4	T5	X1	±G1	Weight [g]	Part no.	Type
		±0.05			±0.05	+0.2				
12	5	2.15	8	6.5	2.15	34.4	4.5	154	1492072	DADM-EP-G6-10
16						37.8				
20	6.8	2.65	10	8	2.65	48.5	2.5	340	1478121	DADM-EP-G6-16
25						55.6				

Ordering data					
	For size	Description	Part no.	Type	PU ¹⁾
Connector sleeve ZBV Datasheets → Internet: zbv					
	12, 16	For centring the intermediate-position module (2 pieces included in the scope of delivery of the intermediate-position module)	560254	ZBV-10-9	10
Centring sleeve ZBH Datasheets → Internet: zbh					
	20, 25	For centring the intermediate-position module (2 pieces included in the scope of delivery of the intermediate-position module)	8137185	ZBH-12-B	10

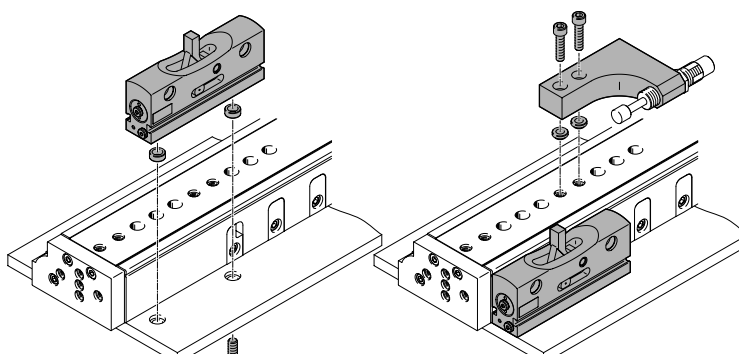
1) Packaging unit

Assembly

To ensure that the shock absorber strikes the stop lever in the centre, we recommended mounting the intermediate-position module directly next to the mini slide (without a gap). It is fastened on the mounting surface using 2 screws and centring sleeves. The shock absorber retainer is then attached to the slide of the mini slide, also using 2 screws and centring sleeves.

Precision adjustment:

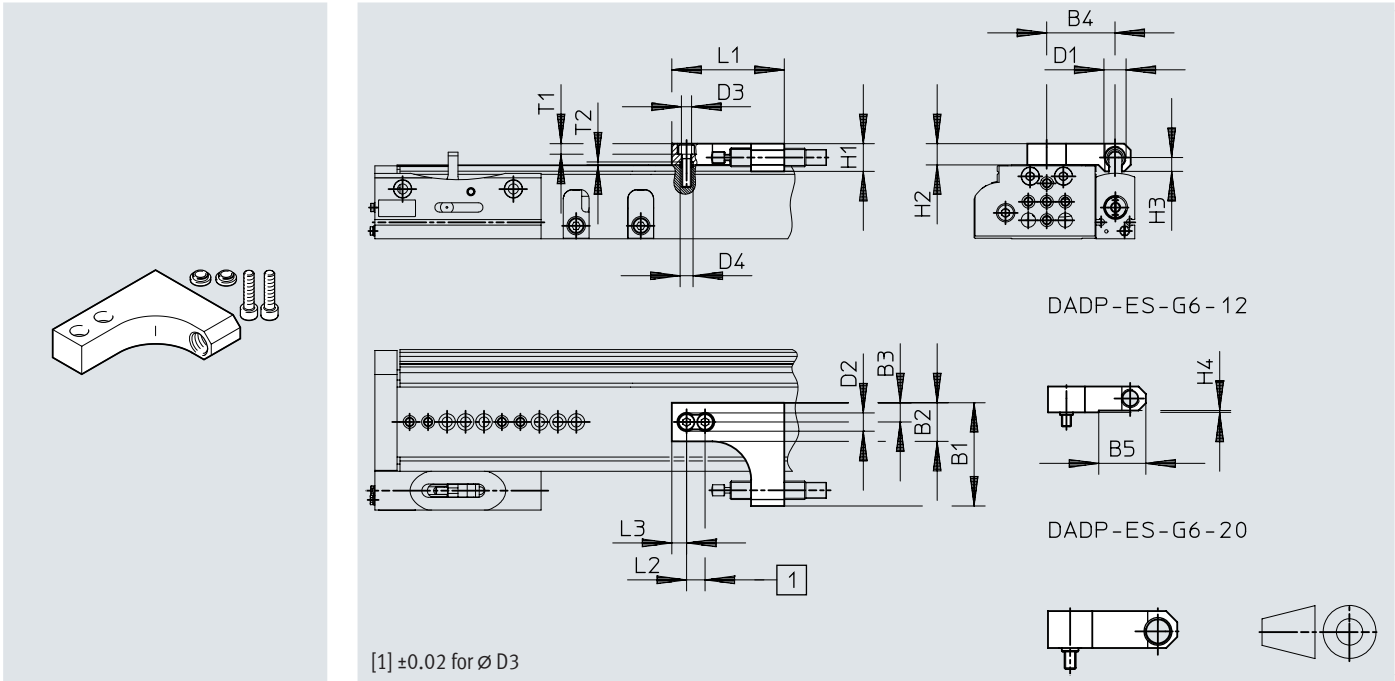
The position can be precisely adjusted via the screw-in depth of the shock absorber. The shock absorber must protrude by at least 1.5 mm.



Accessories

Shock absorber retainer DADP

Material:
Anodised wrought aluminium alloy
RoHS-compliant



Dimensions and ordering data											
For size	B1	B2	B3	B4	B5	D1	D2 ø	D3 ø	D4 ø H7	H1	H2
12	53	20	10	34.5	25.5	M10x1	10	5.5	7	13	14
16	56	21	10.5	37	39.2	M12x1	10	5.5	7	15	12.2
20	70	24	12	47.5	–	M14x1	11	6.6	12	20	20
25	80	30	15	54.5	58	M16x1	11	6.6	12	25	14

For size	H3	H4	L1	L2	L3	T1	T2	Weight [g]	Part no.	Type
12	6.5	1	65	10	10	5.7	1.6	80	1812471	DADP-ES-G6-12
16	7.5	2.8	61	10	8	5.7	1.6	70	1812472	DADP-ES-G6-16
20	9	–	85	20	10	6.4	2.6	185	1812473	DADP-ES-G6-20
25	10	11	80	20	10	6.8	2.6	160	1812550	DADP-ES-G6-25

Ordering data					
	For size	Description	Part no.	Type	PU ¹⁾
Centring sleeve ZBH					
Datasheets → Internet: zbh					
	12, 16	For centring the shock absorber retainer (2 pieces included in the scope of delivery of the shock absorber retainer)	8146544	ZBH-7-B	10
Connector sleeve ZBV					
Datasheets → Internet: zbv					
	20, 25	For centring the shock absorber retainer (2 pieces included in the scope of delivery of the shock absorber retainer)	548806	ZBV-12-9	10

1) Packaging unit

**Note**

- A shock absorber retainer DADP-ES is additionally required when using an intermediate-position module
- Operation without cushioning components is not permitted
- Cushioning components are not included in the scope of delivery
- The size of the shock absorbers for the mini slides and for the relevant shock absorber retainer are identical. Shock absorber selection → Page 51
- The same cushioning component is used for cushioning the intermediate position as for the end positions of the mini slide

Accessories

Ordering data							
	For size	For shock absorber re- tainer	Description	Order code	Part no.	Type	PU ¹⁾
Shock absorber DYEF-...-Y1 Datasheets → Internet: dyef							
	4	–	Elastic cushioning, without metal stop	P	1179810	DYEF-M4-Y1	1
	6	–			1179818	DYEF-M5-Y1	
	8	–			1179831	DYEF-M6-Y1	
	10	–			1179834	DYEF-M8-Y1	
	12	DADP-ES-G6-12			1179837	DYEF-M10-Y1	
	16	DADP-ES-G6-16			1179840	DYEF-M12-Y1	
	20	DADP-ES-G6-20			1179863	DYEF-M14-Y1	
	25	DADP-ES-G6-25			1179879	DYEF-M16-Y1	
Shock absorber DYEF-S-...-Y1 Datasheets → Internet: dyef							
	4	–	Elastic cushioning, without metal stop, short design	E	1152500	DYEF-S-M4-Y1	1
	6	–			1152507	DYEF-S-M5-Y1	
	8	–			1152524	DYEF-S-M6-Y1	
	10	–			1152536	DYEF-S-M8-Y1	
	12	DADP-ES-G6-12			1152959	DYEF-S-M10-Y1	
	16	DADP-ES-G6-16			1153004	DYEF-S-M12-Y1	
	20	DADP-ES-G6-20			1153017	DYEF-S-M14-Y1	
	25	DADP-ES-G6-25			1153023	DYEF-S-M16-Y1	
Shock absorber DYEF-...-Y1F Datasheets → Internet: dyef							
	4	–	Elastic cushioning, with metal stop	P1	548370	DYEF-M4-Y1F	1
	6	–			548371	DYEF-M5-Y1F	
	8	–			548372	DYEF-M6-Y1F	
	10	–			548373	DYEF-M8-Y1F	
	12	DADP-ES-G6-12			548374	DYEF-M10-Y1F	
	16	DADP-ES-G6-16			548375	DYEF-M12-Y1F	
	20	DADP-ES-G6-20			548376	DYEF-M14-Y1F	
	25	DADP-ES-G6-25			548377	DYEF-M16-Y1F	
Shock absorber DYSW Datasheets → Internet: dysw							
	8	–	Progressive shock absorber, at both ends	Y3	548070	DYSW-4-6-Y1F	1
	10	–			548071	DYSW-5-8-Y1F	
	12	DADP-ES-G6-12			548072	DYSW-7-10-Y1F	
	16	DADP-ES-G6-16			548073	DYSW-8-14-Y1F	
	20	DADP-ES-G6-20			548074	DYSW-10-17-Y1F	
	25	DADP-ES-G6-25			548075	DYSW-12-20-Y1F	
Reducing sleeve DAYH Datasheets → Internet: dayh							
	10	–	For DYSW-4-6	–	1165476	DAYH-4	1
	12	DADP-ES-G6-12	For DYSW-5-8		1165480	DAYH-5	
	16	DADP-ES-G6-16	For DYSW-7-10		1165484	DAYH-7	
	20	DADP-ES-G6-20	For DYSW-8-14		1165488	DAYH-8	
	25	DADP-ES-G6-25	For DYSW-10-17		1165491	DAYH-10	

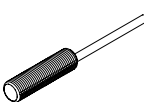
1) Packaging unit

Monitoring with distance sensor SOIA

To monitor the application and condition of the damping elements. Enables predictive maintenance and increases reliability and accuracy.

The following parameters can be monitored:

- Impact velocity
- End position
- Energy consumption
- Residual energy
- Damping reserve

Distance sensor SOIA, inductive							Datasheets → Internet: soia
	Mounting type	Displacement measuring range	Switching output	Electrical connection	Part no.	Type	
	Flush	0 ... 2 mm	PNP/NPN, switchable, Push-pull	Open end	8161194	SOIA-M8PB-PNLK-LE	
		0 ... 4 mm			8161198	SOIA-M12PB-PNLK-LE	
	Not flush				8161196	SOIA-M8PNB-PNLK-LE	
		0 ... 7 mm			8161200	SOIA-M12PNB-PNLK-LE	

Accessories

Ordering data					
	For size	Description	Part no.	Type	PU ¹⁾
Centring sleeve ZBH					Datasheets → Internet: zbh
	4, 6	For centring loads and attachments (6 centring sleeves are included in the scope of delivery of the mini slide)	8146543	ZBH-5-B	10
	8, 10, 12, 16		8146544	ZBH-7-B	
	20, 25		8137184	ZBH-9-B	
Connector sleeve ZBV					Datasheets → Internet: zbv
	8, 10	- For connecting two mini slides DGSL - Sizing information refers to the Y-axis	548802	ZBV-M4-7	3
	12, 16		548803	ZBV-M5-7	
	20, 25		548804	ZBV-M6-9	

1) Packaging unit

Ordering data					
	For size	Description	Part no.	Type	PU ¹⁾
One-way flow control valve GRLA			Datasheets → Internet: grla		
	4, 6, 8	- For regulating speed - Only one GRLA-M3-QS-3 can be mounted on the front with size 4	175041	GRLA-M3-QS-3	1
	10, 12, 16		175038	GRLA-M3	
			20, 25	193137	
193138				GRLA-M5-QS-4-D	
	20, 25		193143	GRLA-1/8-QS-4-D	
			193144	GRLA-1/8-QS-6-D	
			162965	GRLA-1/8-QS-6-RS-B	
				162966	
Push-in fitting QSM			Datasheets → Internet: qs		
	4, 6, 8	For connecting tubing with standard O.D.	153301	QSM-M3-3	10
	10, 12, 16		153304	QSM-M5-4	
	20, 25		153307	QSM-1/8-6	

1) Packaging unit

Proximity switch for mini slide DGSL and intermediate-position module DADM-EP-G6-10						
Ordering data – Proximity switch for C-slot, magneto-resistive Datasheets → Internet: smt						
	Type of mounting	Switching output	Electrical connection, outlet direction of connection	Cable length [m]	Part no.	Type
N/O						
	Inserted in the slot from above	PNP	Cable, 3-core, lengthwise	2.5	551373	SMT-10M-PS-24V-E-2.5-L-OE
			Plug M8x1, 3-pin, lengthways	0.3	551375	SMT-10M-PS-24V-E-0.3-L-M8D
			Plug M8x1, 3-pin, crossways	0.3	551376	SMT-10M-PS-24V-E-0.3-Q-M8D

Ordering data – Proximity switch for C-slot, magnetic reed ¹⁾ Datasheets → Internet: sme						
	Type of mounting	Switching output	Electrical connection, outlet direction of connection	Cable length [m]	Part no.	Type
N/O						
	Inserted in the slot from above	Contacting	Plug M8x1, 3-pin, lengthways	0.3	551367	SME-10M-DS-24V-E-0.3-L-M8D
			Cable, 3-core, lengthwise	2.5	551365	SME-10M-DS-24V-E-2.5-L-OE
			Cable, 2-core, lengthwise	2.5	551369	SME-10M-ZS-24V-E-2.5-L-OE
	Inserted into the slot lengthwise	Contacting	Plug M8x1, 3-pin, lengthways	0.3	173212	SME-10-SL-LED-24
			Cable, 3-core, lengthwise	2.5	173210	SME-10-KL-LED-24

1) Proximity switches are not permitted on the mini-slide DGSL-4.

Accessories

Proximity switch for intermediate-position module DADM-EP-G6-16

Ordering data – Proximity switch for T-slot, magneto-resistive

Datasheets → Internet: smt

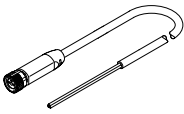
	Type of mounting	Switching output	Electrical connection	Cable length	Part no.	Type
N/O						
	Inserted in the slot from above, flush with the cylinder profile, short design	PNP	Cable, 3-core	2.5 m	574335	SMT-8M-A-PS-24V-E-2.5-OE
			Plug M8x1, 3-pin	0.3 m	574334	SMT-8M-A-PS-24V-E-0.3-M8D
			Plug M12x1, 3-pin	0.3 m	574337	SMT-8M-A-PS-24V-E-0.3-M12
		NPN	Cable, 3-core	2.5 m	574338	SMT-8M-A-NS-24V-E-2.5-OE
			Plug M8x1, 3-pin	0.3 m	574339	SMT-8M-A-NS-24V-E-0.3-M8D

Ordering data – Proximity switch for T-slot, magnetic reed

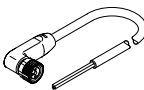
Datasheets → Internet: sme

	Type of mounting	Switching output	Electrical connection	Cable length	Part no.	Type
N/O						
	Inserted in the slot from above, flush with the cylinder profile	Contacting	Cable, 3-core	2.5 m	543862	SME-8M-DS-24V-K-2.5-OE
				5.0 m	543863	SME-8M-DS-24V-K-5.0-OE
			Cable, 2-core	2.5 m	543872	SME-8M-ZS-24V-K-2.5-OE
			Plug M8x1, 3-pin	0.3 m	543861	SME-8M-DS-24V-K-0.3-M8D
	Inserted in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-core	2.5 m	150855	SME-8-K-LED-24
			Plug M8x1, 3-pin	0.3 m	150857	SME-8-S-LED-24

Connecting cables NEBA, straight

	Electrical connection 1, connection technology	Electrical connection 2, connection technology	Electrical connection 2, number of pins/cores	Cable length	Part no.	Type
	M8x1 A-coded to EN 61076-2-104	Open end	3	2.5 m	8078223	NEBA-M8G3-U-2.5-N-LE3
				5 m	8078224	NEBA-M8G3-U-5-N-LE3

Connecting cables NEBA, angled

	Electrical connection 1, connection technology	Electrical connection 2, connection technology	Electrical connection 2, number of pins/cores	Cable length	Part no.	Type
	M8x1 A-coded to EN 61076-2-104	Open end	3	2.5 m	8078230	NEBA-M8W3-U-2.5-N-LE3
				5 m	8078231	NEBA-M8W3-U-5-N-LE3